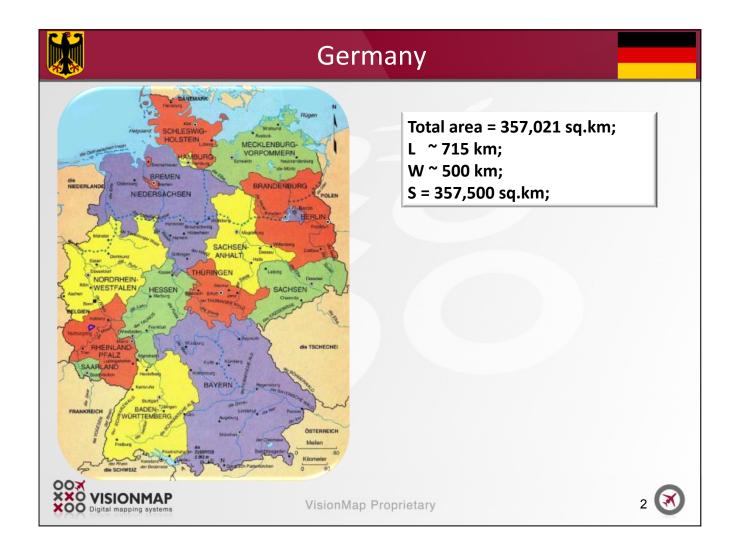
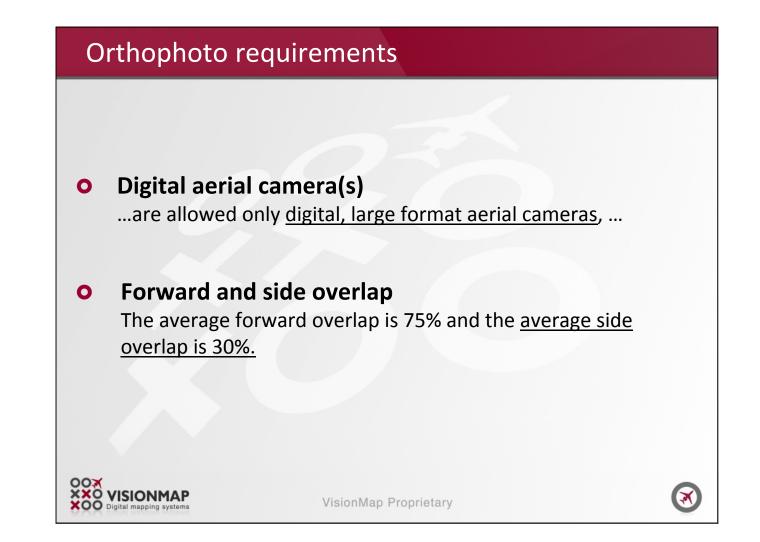


High Throughput Aerial Photography, Ortho & 3D Processing with VisionMap A3 EDGE mapping system

54th Photogrammetric Week

September 2013





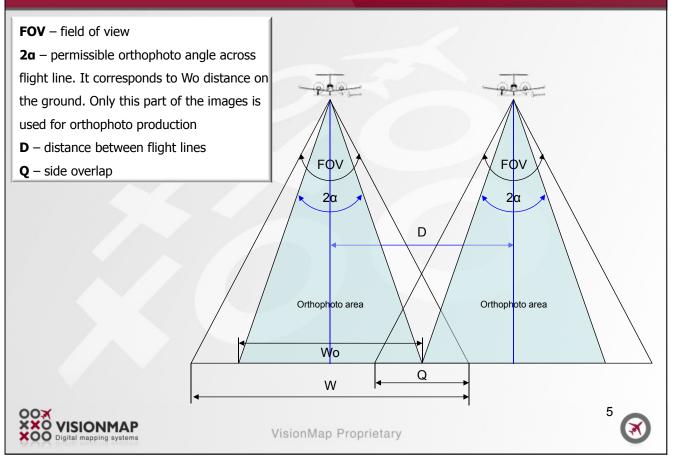
Digital cameras main parameters

	1			
Camera	F (mm)	Pixel size (μ)	Frame size (pix)	FOV (deg)
EAGLE 210	210	5.2	20, 010 * 13,080	27.8
EAGLE 80	80	5.2	20,010 * 13,080	66.1
UC-Xp	100	6.0	17,310 * 11,310	54.9
UC-X	100	7.2	14,430 * 9,420	54.9
UC-Xp wa	70	6.0	17,310 * 11,310	73.1
UC-L	70	7.2	9,600 * 6,500	52.6
DMC II 250	112	5.6	17,216 * 14,656	46.6
DMC II 230	92	5.6	15,104 * 14,400	49.4
DMC II 140	92	7.2	12,096 * 11,200	50.7
DMC	120	12	13,824 * 7,680	69.3
ADS 80	62.77	6.5	12,000 * 7,530	63.7
RC30/150	150	15	16,000 * 16,000	77.3
RC30/300	300	15	16,000 * 16,000	43.6



VisionMap Proprietary

Vertical aerial survey scheme



From side overlap to 2α or building leaning

Camera	Side overlap (%)	Orthophoto angle 2α (deg)	Building leaning (%)
EAGLE 210	30	19.7	17.3
EAGLE 80	30	49.0	45.5
UC-Xp	30	40.0	36.4
UC-X	30	40.0	36.4
UC-Xp wa	30	54.9	51.9
UC-L	30	38.1	34.6
DMC II 250	30	33.5	30.1
DMC II 230	30	35.7	32.2
DMC II 140	30	36.7	33.1
DMC	30	51.6	48.4
ADS 80	30	47.0	43.5
RC30/150	30	58.5	56.0
RC30/300	30	31.3	28.0



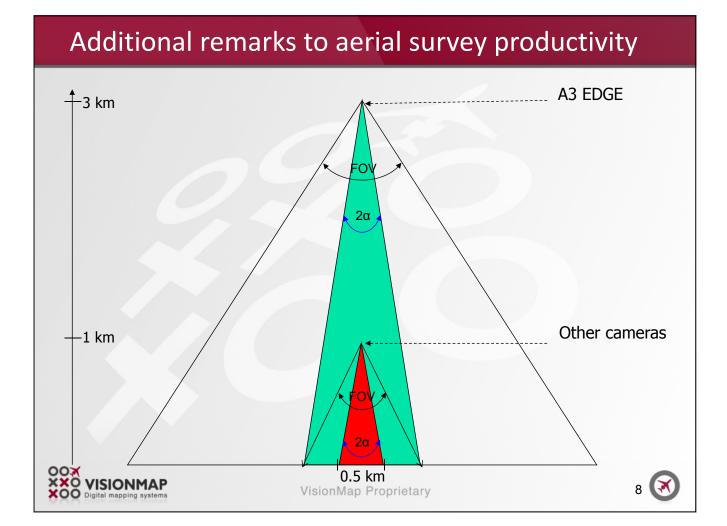
VisionMap Proprietary

From 2α to side overlap

Camera	Orthophoto angle 2α (deg)	Side overlap (%)
A3 EDGE	55	30 - 66
EAGLE 210	55	No side overlap
EAGLE 80	55	20
UC-Xp	55	0.1
UC-X	55	0.1
UC-Xp wa	55	30
UC-L	55	No side overlap
DMC II 250	55	No side overlap
DMC II 230	55	No side overlap
DMC II 140	55	No side overlap
DMC	55	25
ADS 80	55	17
RC30/150	55	35
RC30/300	55	No side overlap



VisionMap Proprietary



/

7 😿

Intermediate conclusions

- Flying higher with the same 2 alpha angle yields higher productivity
- Flying higher with longer focal length yields the same or even higher image resolution
- Large FOV provides large side overlap which leads to a more robust and accurate photogrammetric solution
- Large FOV provides large variety in orthophoto angle from very small to very large angles, still maintaining appropriate side overlap.
- Large FOV provides oblique images in the same flight

VisionMap Proprietary



What have we learned from this exercise?

- 30% side overlap permits a 55 degree orthophoto angle or 52% building leaning
- Not all cameras can fly with a 55 degree ortophoto angle
- 55 degree orthophoto angle will be used for further considerations





Aircrafts

Aircraft	Practical Service Ceiling (m)	Practical Service Ceiling (feet)	Cruise Speed (km/h)	Cruise Speed (knot)	Image GSD (cm)
Gulfstream G650	13,213	43,353	904	488	32.59
Learjet 23, 25	11,658	38,249	834	450	28.76
King Air B200	9,095	29,841	536	289	22.44
Cessna 210, 303, 402, 402	6,500	18,128	350	189	13.63

Comments: The image GSD is calculated for A3 EDGE aerial camera at service ceiling.



VisionMap Proprietary

Aerial survey of Germany with A3 EDGE/S

Aircraft	Image GSD (cm)	Altitude (feet)	Ground speed (knot)	Ortho GSD (cm)		Number of Flight lines	Aerial Survey Productivity (sq.km/hour)	Total Aerial Survey Time (day)
Gulfstream G650	25	33,250	488	30	10,024	51	9,060	9
Learjet 23, 25	21	27,700	430	25	8,354	61	6,653	12
Learjet 23, 25	17	22,200	360	20	6,683	76	4,456	18
King Air B200	12	16,600	270	15	5,012	10	2,506	31
Cessna 210,, 404	8	11,100	180	10	3,341	151	1,114	68

Comments:

- 1. For these calculations the mapping area is presented as a rectangle of size 500 km x 715 km = 357,500 sq.km;
- 2. $2\alpha = 55^{\circ}$ (it corresponds to 30% side overlap for UC Xp wa and 35% side overlap for RC30/150) ;
- 3. Forward overlap 55%; Side overlap larger than 55%;
- 4. Aerial survey day 5 hours;
- 5. Aerial survey time per one A3 EDGE/S camera including time for turns (5 min) between flight lines;



VisionMap Proprietary

11

Aerial survey of Germany with A3 EDGE/S-CIR

Aircraft	Image GSD (cm)	Altitude (feet)	Ground speed (knot)	Ortho GSD (cm)		Number of Flight lines	Productivity	
Gulfstream G650	25	33,250	340	30	7,000	72	4,413	18
Learjet 23, 25	21	27,700	280	25	5,841	87	3,029	26
Learjet 23, 25	17	22,200	230	20	4,673	108	1,990	39
King Air B200	12	16,600	180	15	3,222	156	1,074	70
Cessna 210,, 404	8	11,100	160	10	1,482	338	439	169

Comments:

- 1. For these calculations the mapping area is presented as a rectangle of size 500 km x 715 km = 357,500 sq.km;
- 2. $2\alpha = 55^{\circ}$ (it corresponds to 30% side overlap for UC Xp wa and 35% side overlap for RC30/150) ;
- 3. Forward overlap 55%; Side overlap larger than 55%;
- 4. Aerial survey day 5 hours;
- 5. Aerial survey time per one A3 EDGE/S-CIR camera including time for turns (5 min) between flight lines;



VisionMap Proprietary

Mapping of Germany with LightSpeed SW

Ortho GSD (cm)	Image GSD (cm)	RGB Processing Productivity (sq.km/day)	RGB Total Processing Time (day)	RGB+NIR Processing Productivity (sq.km/day)	RGB+NIR Total Processing Time (day)
30	25	9,000	40	6,000	60
25	21	6,250	58	4,000	90
20	17	4,000	90	2,500	143
15	12	2,250	159	1,500	239
10	8	1,000	358	600	596

Comments:

- 1. Total area 357,500 sq.km;
- 2. Processing time is calculated per one standard A3 LightSpeed processing system ;
- 3. Processing time does not include DSM/DTM processing and manual processes like cut-line editing and QA;



VisionMap Proprietary

13

A3 EDGE mapping system



Aerial survey camera

Ground processing system

15 🔇



VisionMap Proprietary

Aerial cameras: A3 CORE, A3 EDGE



Technical characteristics of A3 CORE & A3 EDGE

Camera Model	A3 CORE	A3 EDGE				
Weight (kg)	38					
Size (cm)	50*6	50*60				
Focal length (mm)	3	00				
Color	RGB or	RGB+CIR				
Color Depth (bit)		12				
Image motion compensation	Forward, Roll, Vibration (FMC, RMC, VC)					
Max FOV (°)	72	110				
Vertical aerial survey	Yes	Yes				
Oblique aerial survey	No	Yes				
CCD pixel size (µ)	7.4	7.4				
Maximal footprint (pix)	49,000 x 9,600	78,000 x 9,600				
Maximal image volume (Mpix)	457	718				
On-board storage capacity for continues acquisition (hours)	6 - 9	6 – 7				



VisionMap Proprietary

Aerial Survey Productivity

	Orthophoto GSD (cm)	5	10	15	20	25	30
	Image GSD (cm)	4.17	8.33	12.50	16.67	20.83	25.00
	Altitude (feet)	5,542	11,084	16,626	22,168	27,709	33,251
	Ground speed (knot)	160	250	350	400	450	500
A3 CORE/S	Permissible orthophoto angle 2α (deg)	25	35	38	38	38	38
D	Distance between flight lines (m)	712	2,024	3,315	4,420	5,526	6,631
	Aerial Survey Productivity (sq.km/hour)	223	941	2,149	3,275	4,605	6,140
	Altitude (feet)	5,542	11,084	16,626	22,168	27,709	33,251
	Ground speed (knot)	160	250	310	360	430	490
A3 EDGE/S	Permissible orthophoto angle 2α (deg)	25	35	45	55	60	65
	Distance between flight lines (m)	712	2,024	3,988	6,683	9,265	12,268
	Aerial Survey Productivity (sq.km/hour)	211	937	2,290	4,456	7,378	11,133

Comments:

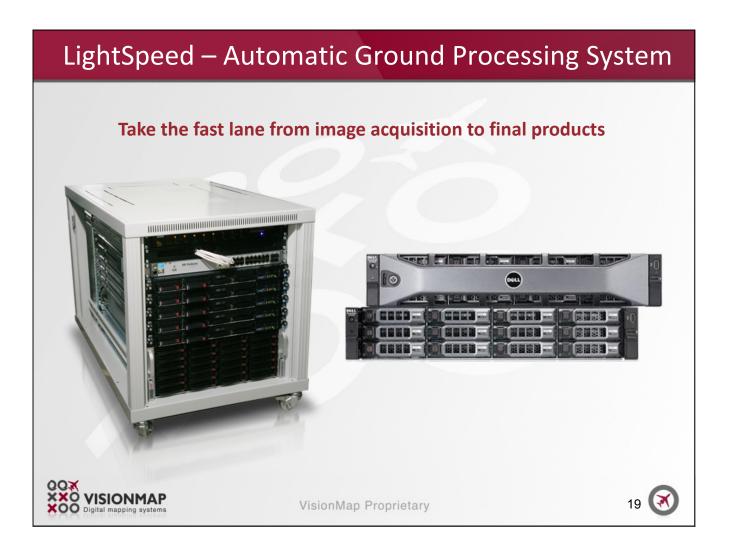
1. $2\alpha = 65^{\circ}$ corresponds to 20% side overlap for RC30/150 ;

2. For A3 EDGE: forward overlap – 55%; side overlap – larger than 55%;





17



A3 LightSpeed Cluster Hardware Configuration

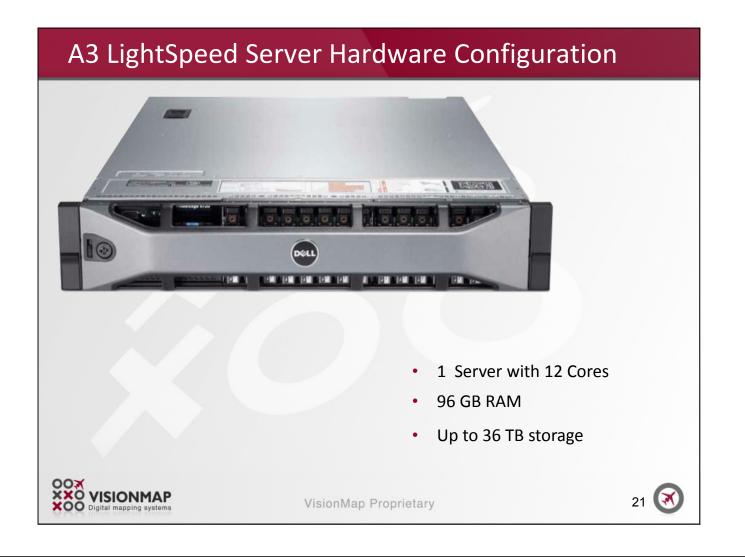


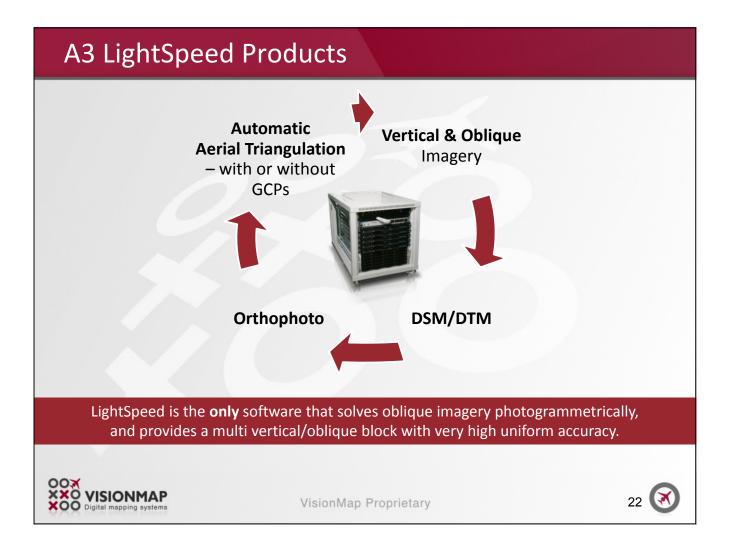
- 1 x Manager Server
- 4 x Multi Core Processing Servers, 12 cores each, 96 GB RAM
- High Capacity Storage (48 TB)
- Fast network switch (10 GB)
- 1 x Working station



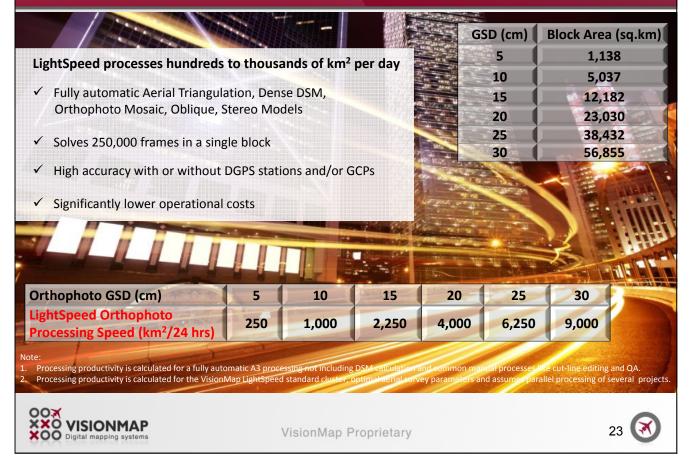
VisionMap Proprietary

20 📀





A3 LightSpeed - Fastest Processing



Stuttgart University Accuracy Certification

	Forward	Side						RMS-	RMS-	RMS-
Camera	overlap (p%)	overlap (q%)	Strips	GCP	RMS East (m)	RMS North (m)	RMS Z (m)	E/GSD (%)	N/GSD (%)	Z/GSD (%)
A3 (Case 5b)	52%	86%	8	5	0.020	0.023	0.052	33%	39%	87%
A3 (case 6b)	52%	86%	8	10	0.015	0.018	0.030	24%	30%	50%
A3 (Case 7b)	52%	73%	5	5	0.017	0.023	0.050	28%	39%	84%
A3 (Case 8b)	52%	73%	5	10	0.016	0.017	0.035	27%	28%	58%

Notes:

- Average altitude: 1972 m
- Flight line direction: east-west, bi-directional
- Average ground speed: 113 knot
- Difference in ground speed in two directions: 23 knot
- GSD: 6 cm
- Number of flight line: 8
- Average forward overlap: p = 52%
- Average side overlap: q = 86% (when all 8 flight lines are considered) or 73% (when 5 flight lines are considered)
- Number of check points: 136

The complete report can be found on www.visionmap.com/files/IFP_Visionmap_A3_Report.pdf.



VisionMap Proprietary

Highly Accurate Aerial Triangulation (AT)

GSD (cm)	5	5		10		15		20		25		D
	RMSxy	RMSz										
AT (internal, pix)	0.5	1.0	0.5	1.0	0.5	1.0	0.5	1.0	0.5	1.0	0.5	1.0
AT - PPP												
without GCP	20.0	22.5	25.0	30.0	35.0	40.0	40.0	45.0	45.0	50.0	50.0	55.0
(abs. in cm)												
AT - DGPS												
without GCP	10.0	12.5	15.0	17.5	20.0	22.5	25.0	27.5	30.0	32.5	35.0	37.5
(abs. in cm)												
AT - DGPS \ PPP												
with GCP	4.0	5.0	6.0	7.5	7.5	10.0	10.0	14.0	12.5	18.0	15.0	21.0
(abs. in cm)												

Notes

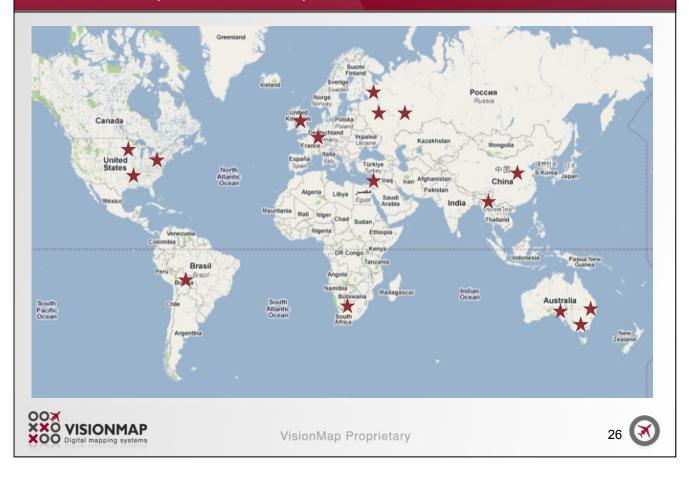
- Assuming PPP accuracy: RMSxy and RMSz not more than 18 cm / Assuming DGPS accuracy: RMSxy and RMSz – not more than 8 cm.
- Forward overlap not less than 55%; Side overlap not less than 60%.
 Number of strips in one AT block not less than 2; Number of sweeps in one strip not less than 20.
- GCP signalized points with coordinates in WGS84; GCP placement - every second strip every 15th sweep;
- Accuracy assessment in WGS84; Accuracy assessment on GCPs- regarding check points which are located between outside strips of the block.
- AT (internal) AT accuracy assessed on tie points.
- Check Points Accuracy: RMSxy and RMSz not more than 2.5cm.

25



VisionMap Proprietary

VisionMap's Global Operation



Some of Our Customers





