Mobile Mapping for Earthworks Monitoring

A Case Study on the Convergence of Photogrammetry with Advanced Positioning Techniques for Maximum Productivity and Accuracy

The Arabian Canal Experience



Dr. Nedal Al-Hanbali

/15/2009

Introduction

- This paper presents a case study on the efficiencies and practicality of using mobile mapping on a large-scale Earth moving project for Real Estate development
- Mobile Mapping: Collecting geo-spatial measurements from a moving platform using advanced photogrammetric and positioning technology

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Overview

LI MITLESS LLC 2008 © A DUBAI WORLD COMPANY The Project The Challenge The Solution: Mobile Mapping Quality Control Methodology Sample Data Products Accuracy Assessment Sample Final Deliverables Summary

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The Project



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The Project: Arabian Canal, Dubai

75 km man-made canal complete with terraced landscaping Mixed use real estate, developed by some of the worlds top firms



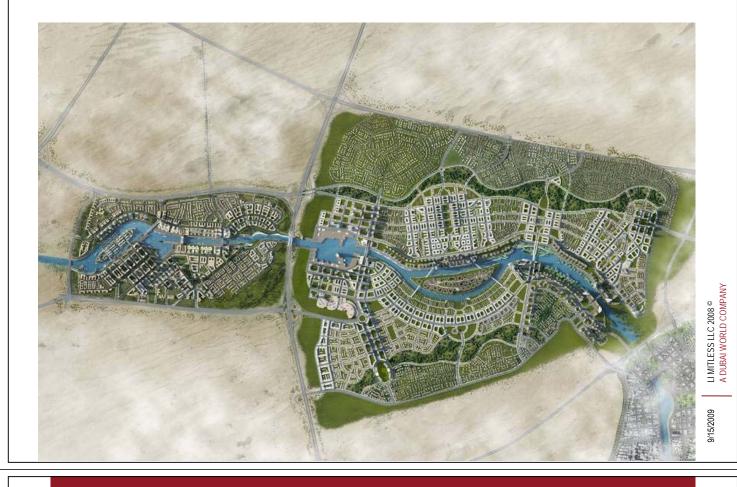
http://www.arabiancanal.com

The Project: Arabian Canal, Dubai

Limitless responsible for managing the overall design and construction, as well as developing an area in excess of 10,000 hectares



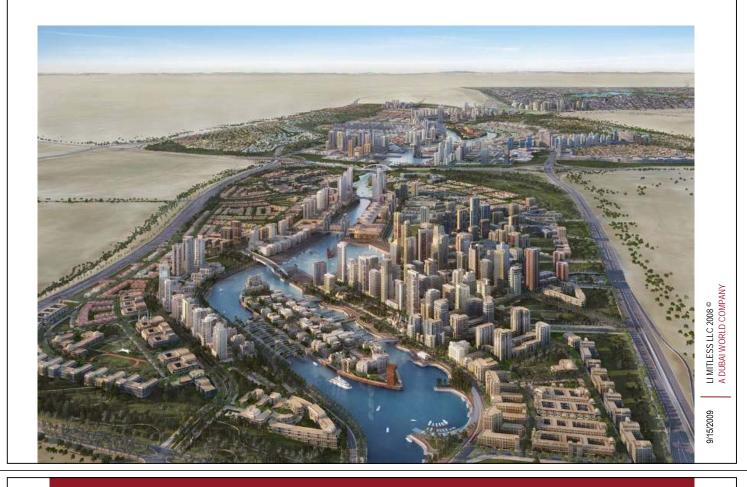
The Project: Arabian Canal, Dubai



The Project: Arabian Canal, Dubai



The Project: Arabian Canal, Dubai



The Challenge

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The Challenge: Earthworks Monitoring

Canal Completion within <i>3 to 5 years</i> <i>Requires 24 hours operation, 7 days a week!</i>	
Earthworks monitoring:	
Monitor and measure dig and deposit on 24 hour cycle for	
– Progress	
 Visualization (quality control, marketing) 	
– Invoicing	
Data Requirements:	
Absolute accuracy 10 cm RMS (minimum)	
Depths up to 55 m	3 © MPANY
Widths greater than 300 m, depending upon slope	LC 2008 RLD CO
Collection Constraints:	LI MITLESS LLC 2008 © A DUBAI WORLD COMPANY
Only able to collect data between shift changes	
No guaranteed access to edge of canal	9/15/2009
Huge area to collect: 100 hectares within hours Dr. Nedal Al-Hanbali	9/15/

Data Collection Options

Static survey (Total Station/GPS/3D Scanner) Pros:

- Proven technology
- High accuracy
- Relatively low capital costs

Cons:

- Many crews and equipment to cover large area => high personnel costs, many data sets to merge, logistical nightmare for quality control
- Access required to edge of canal, in canal among large earth moving equipment => dangerous
- Manual equipment setup and collection => slow

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Mobile Mapping (helicopter and/or vehicle based photogrammetry and LIDAR)

Pros:

- No set up required => fast
- Only 1 or 2 data sets to merge/quality control => high reliability
- Single pilot or driver => low personnel costs
- One set of equipment can cover large area => efficient
- Remote acquisition => safe

Cons:

- Relatively High capital costs
- Unproven accuracy
- Logistically complex and expensive (esp. airborne)

Trade-off Study

Analysis showed:

Significant risk static methods could not complete collection in required times

Could result in huge cost overruns if progress delayed and not detected in time

Improved efficiencies of mobile over large area should offset higher capital costs

Fairly low risk accuracy could not be met by mobile

Conclusion:

Employ mobile mapping to eliminate schedule risk

Reduce accuracy risk by deploying airborne *and* land systems for redundancy

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Choosing the Right Mobile Mapping Sensors

- Like in static surveying, many different options available to do a job Some are very expensive!
- Challenge is to understand the requirements well enough to choose those sensors that meet the requirements while at the same time minimizing capital cost:

The right tool for the job

How to do this? *Come to PhoWo to learn what is state of the art in the industry!*

Airborne Requirements

- Provide orthophoto Maps of construction area for planning and visualization:
 - Ground Sample Distance: 10 cm (max), Ortho accuracy 12 cm RMS.
- Provide point measurements for volume calculations of cut/fill areas:
 - Points spacing 25 cm to 1.5 m, accuracy 10-12 cm RMS (max) Altitudes from 200 to 450 m

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Airborne System: Applanix DSS + LIDAR

- Applanix DSS 439 camera system plus Q240i Laser scanner system mounted in Bell 206 heli pod
- Complete workflow software to generate orthomosaic maps, DEM, filtered point clouds ready for volume calculations
- Reasons:
 - DSS a turn-key, low-cost fully integrated mapping solution with GNSS, IMU, Flight Management system and ortho mapping software meeting GSD and accuracy requirements
 - DSS is certified mapping grade by USGS
 - Q240i meets point cloud density, range and accuracy requirements at relatively low cost

Deliverables: Maximum One Week from flying

Airborne System: Applanix DSS + LIDAR



Electronics



Pod with Camera and Laser

GNSS Antenna





Pod



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Terrestrial Requirements

- Provide point measurements for volume calculation of cut/fill areas Collection within one hour or less
- Ranges up to 300 m
- Point spacing 25 cm to 1.5 m, accuracy 10 cm RMS (max)
- Accuracy must be maintained even at bottom of dig with GPS satellites highly masked
- Georeferenced videolog of scanned area for visualization

Terrestrial System: Trimble LANDMark

- Trimble LANDMark mobile mapping system configured with single video camera and Q240i laser scanner, highest accuracy RLG IMU (POS LV 610)
- Complete workflow sw for georeferencing video, and *same workflow* as airborne system for generating filtered point clouds
- Reasons:
 - Only needed single camera and scanner since always driving in and out of or around dig
 - Q240 meets point cloud density requirements and accuracy at low cost
 - Only highest accuracy IMU could maintain position accuracy during outages

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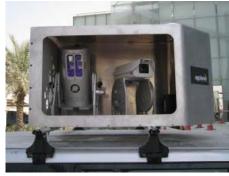
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Terrestrial System: Trimble LANDMark



Electronics



Pod with Camera and Laser

GNSS Antenna







Key Features

Same laser scanner used in air and on ground

Built-in back up

Consistent error characteristics

Same georeferencing workflow (Differential GNSS - Inertial processing)

Same workflow used to generate/filter point clouds, generate DSM and do volume calculations

Check DSM accuracy against each other

Merge data sets

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Quality Control



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Quality Control Methods

Establish dedicated network of GNSS stations

Establish control points in and around project areas:

Permanent

Temporary

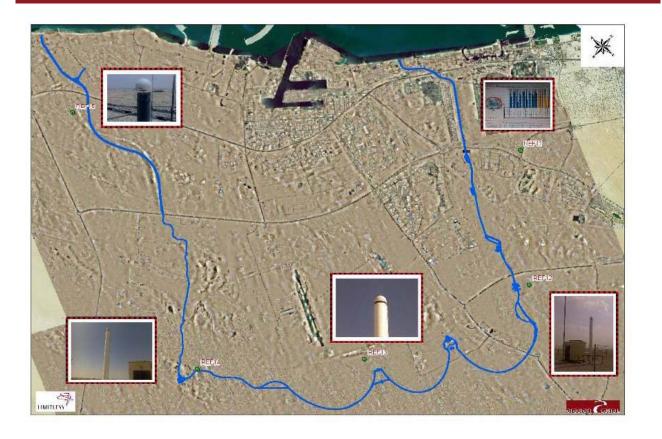
Establish local V datum and use throughout entire project

Validate map and point cloud products against each other, control points and V datum, before generating final products

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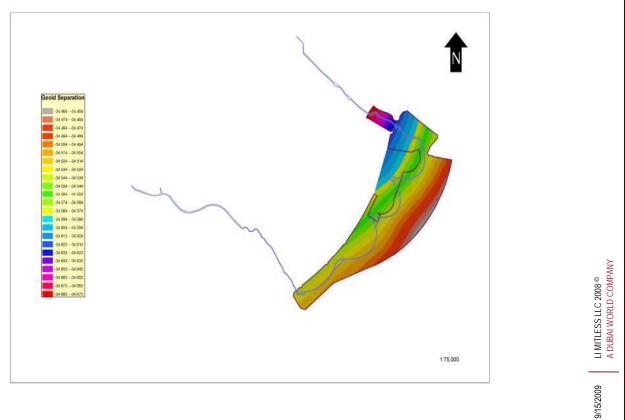
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GNSS Reference Station Layout



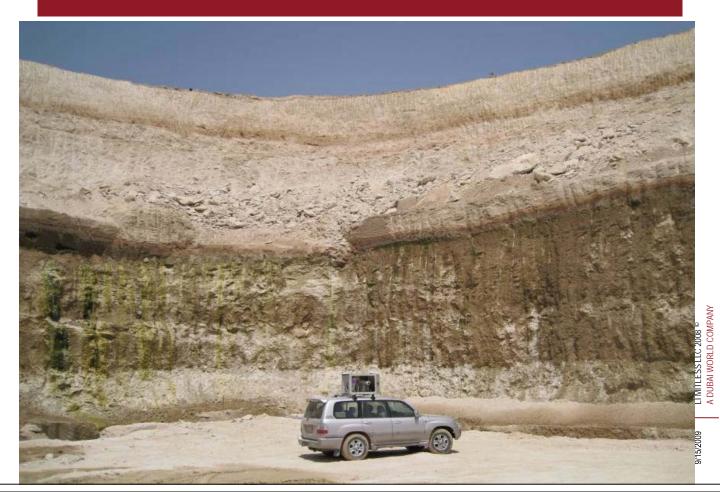
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Vertical Datum



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Why GNSS is poor... (and QC so important!)



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Sample Data Products

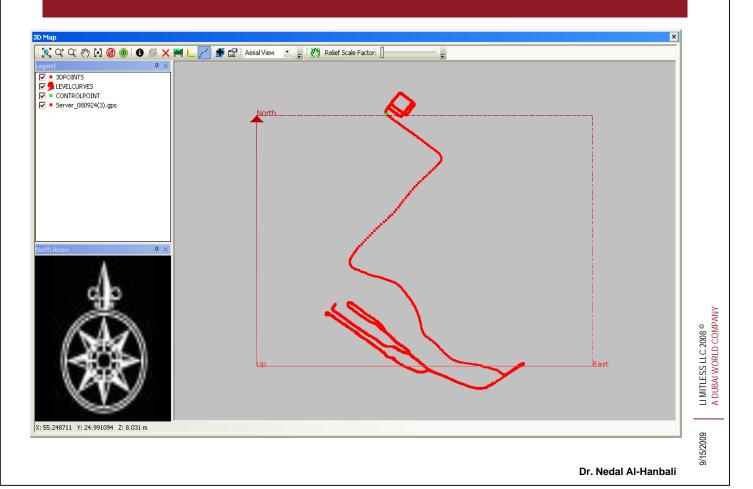


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Typical DSS Trajectory

 TURDENDING
 TURDEND

Sample LANDMark Trajectory

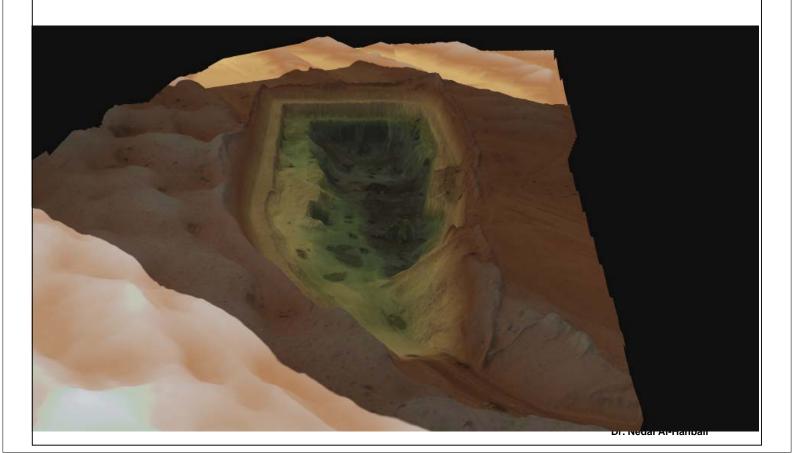


Orthomosaic Map of Dig

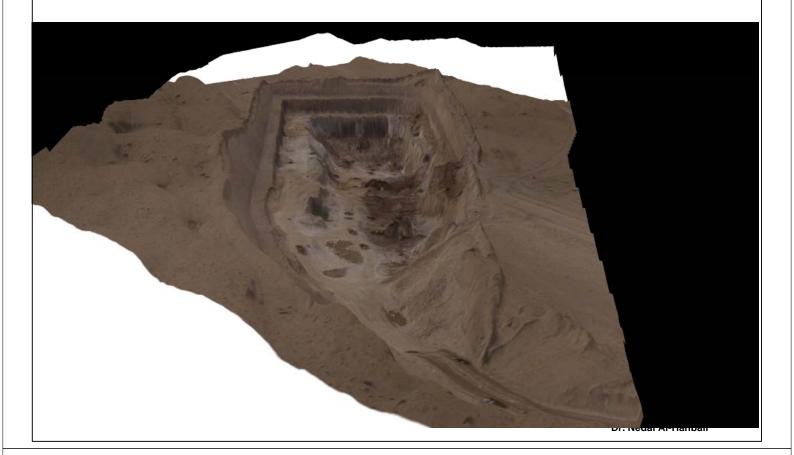




Digital Surface Model (Airborne)



Digital Surface Model (Airborne)



Orthomosaic Map of Deposit

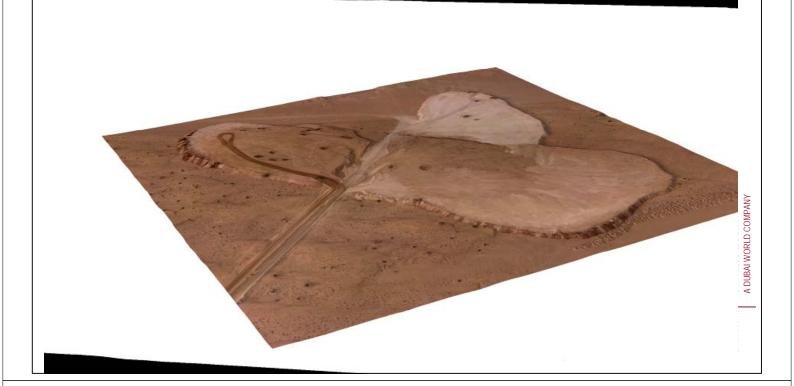


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Digital Surface Model (Airborne)



View of Dig



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Local Hazards!



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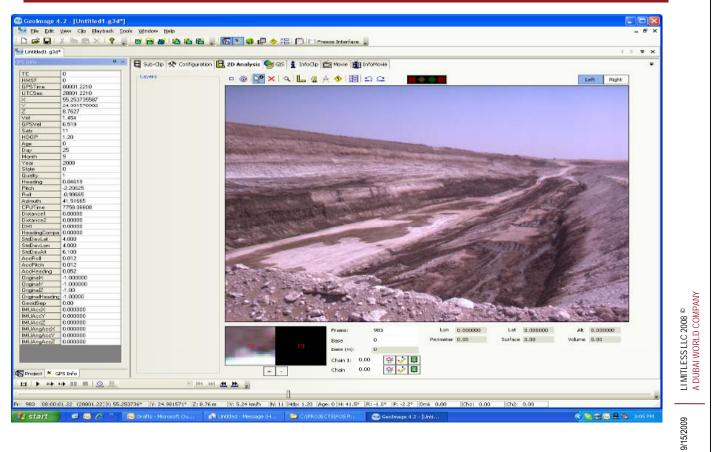
View of Dig



View of Dig



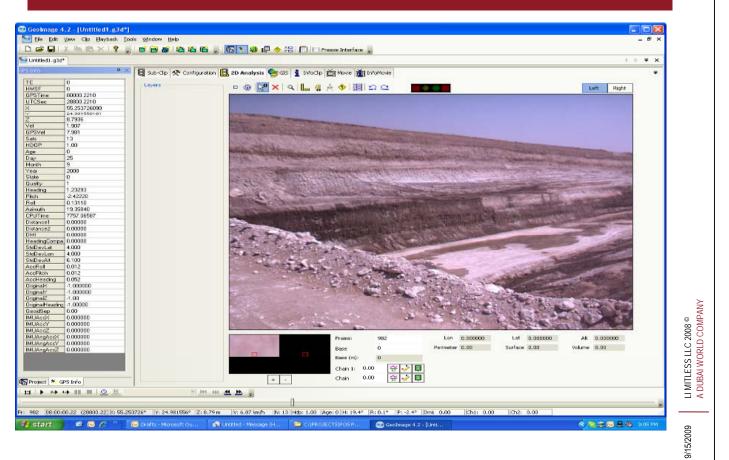
Georeferenced Video



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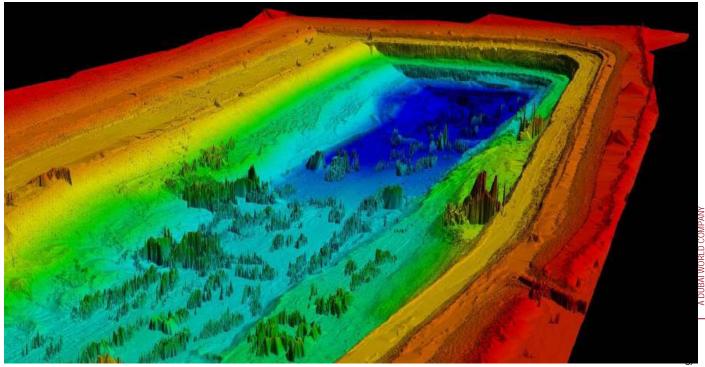
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Georeferenced Video



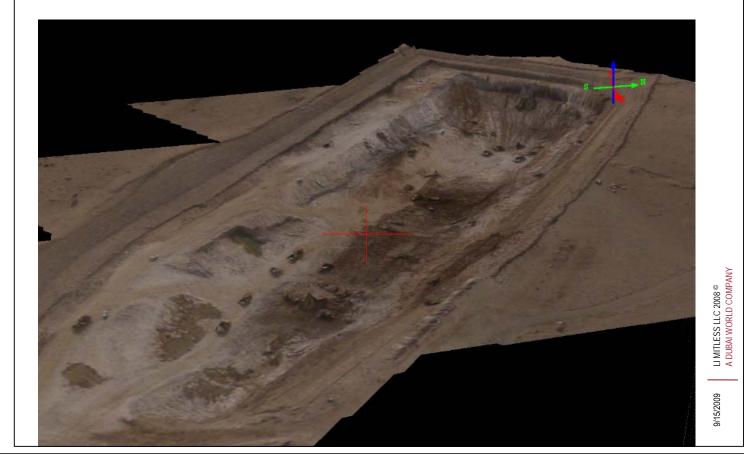
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Digital Surface Model (Terrestrial)



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Digital Surface Model (Terrestrial)



Accuracy Assessment



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Accuracy Assessments

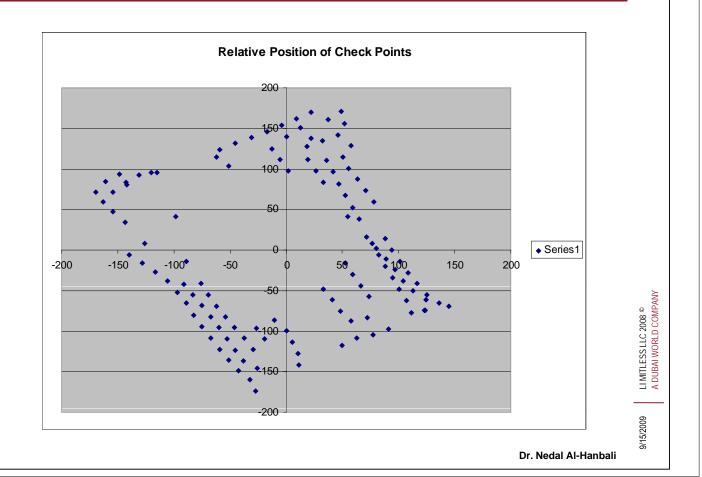
Method 1: Traditional GCP analysis established using GPS (orthomaps and DSM)

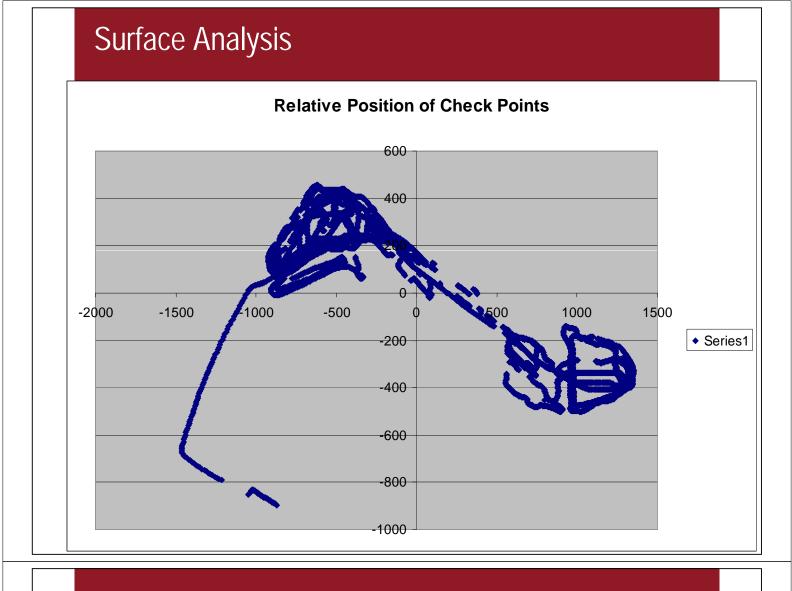
Method 2: Utilize car mounted RTK GNSS to get very dense point clouds of chosen areas and rings around the site (ie use RTK GNSS to create a reference surface model to compare to LANDMark and DSS LIDAR DSM)

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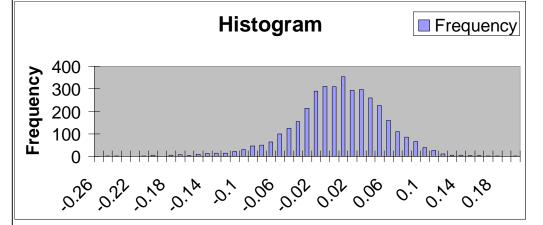
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Checkpoint Analysis

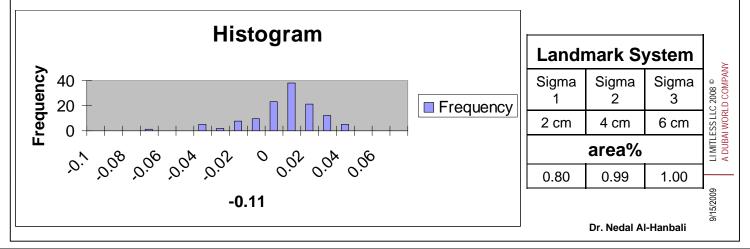




Typical Results, Vertical



DSS System			
Sigma 1	Sigma 2	Sigma 3	
5 cm	10 cm	15 cm	
area%			
0.7582	0.9588	0.9917	



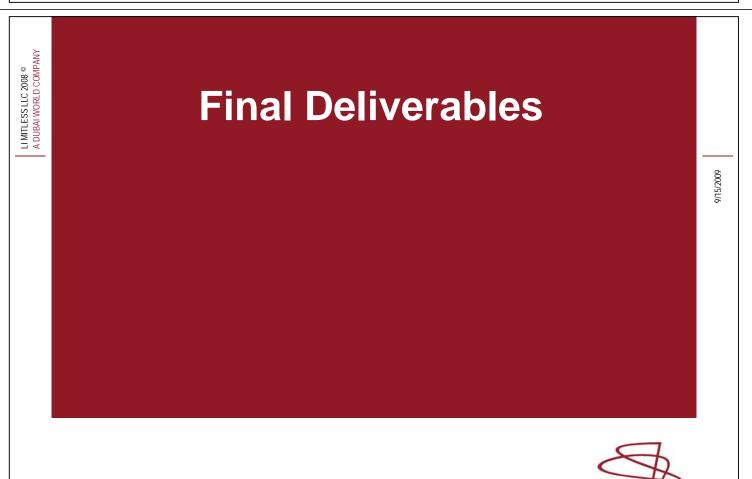
Vertical Accuracy Results

Results from various tests for both LANDMark and DSS systems: Average height offset: 6 to 8 cm Standard deviation: 3 to 6 cm RMS: 8 to 9 cm

Notes:

systematic errors in GPS measurements are about 2-5 cm based on various aspects related to antenna base height due to terrain tilt (car tilting to one or to the other side); air-tires level.

In the area under heavy machinery work, errors vary from 5 to 15 cm due to Truck operation in the AOI changing ground heights.





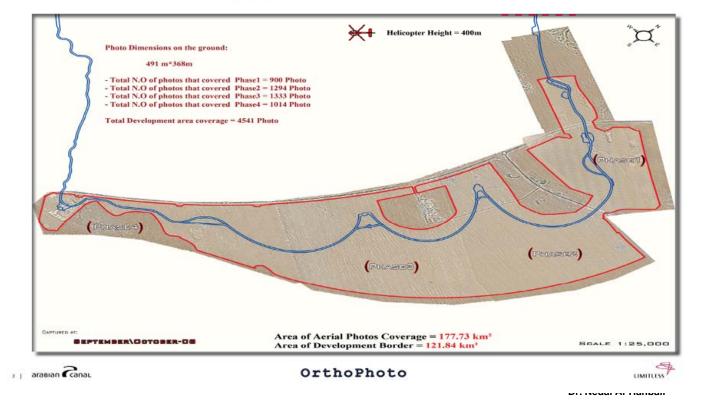
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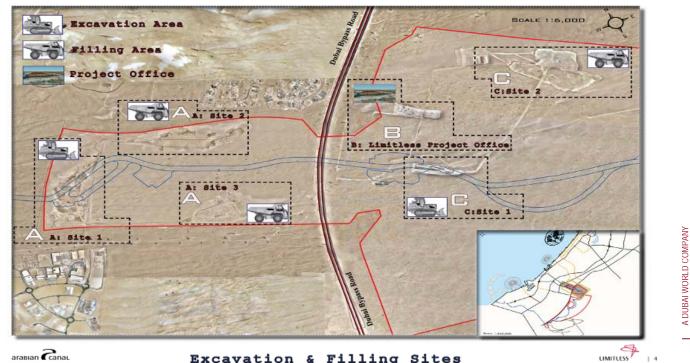
Planning Map

DEVELOPMENT PHASES (1,2,3,4)



Active Areas Map

PHASE 1:

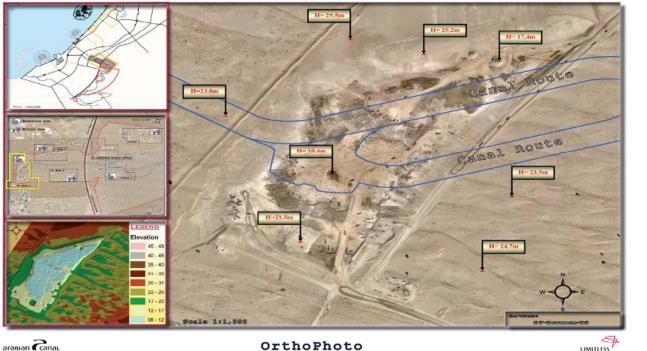


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Excavation & Filling Sites

2D Progress Map

(A:Site 1): Deep Excavation



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PHASE 1

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PHASE 1

3D Progress Map

(A:Site 1): Deep Excavation

LEGEND Elevation 45 - 49 40 - 45 35 - 40 31 - 35 26 - 31 22 - 26 17 - 22 12 - 17 08 - 12

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Depth Color Coded

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3D Progress Map

(A:Site 1): Deep Excavation



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Perspective View

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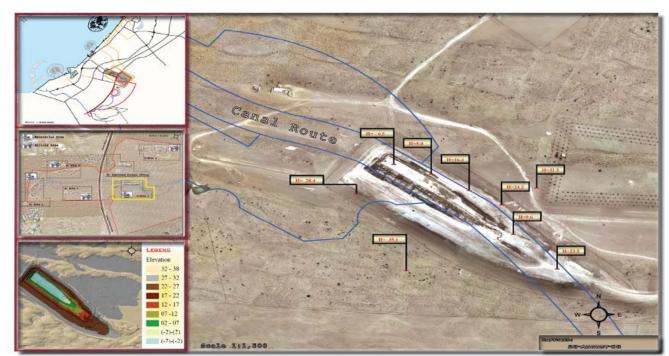
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PHASE 1

2D Progress Map

(C:Site 1): Deep Excavation

PHASE 1



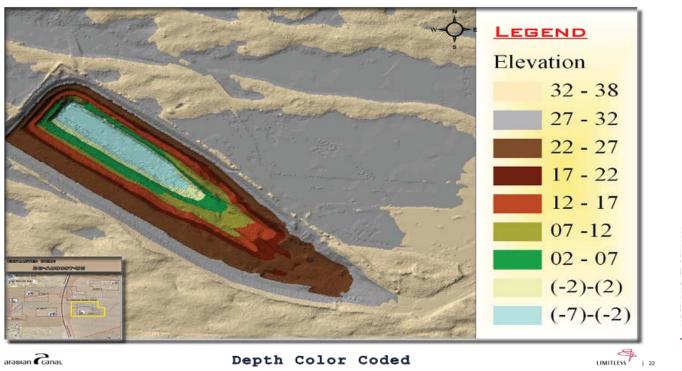
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3D Progress Map

(C:Site 1): Deep Excavation



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Depth Color Coded

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PHASE 1

1 22

6

PHASE 1

3D Progress Map

(C:Site 1): Deep Excavation

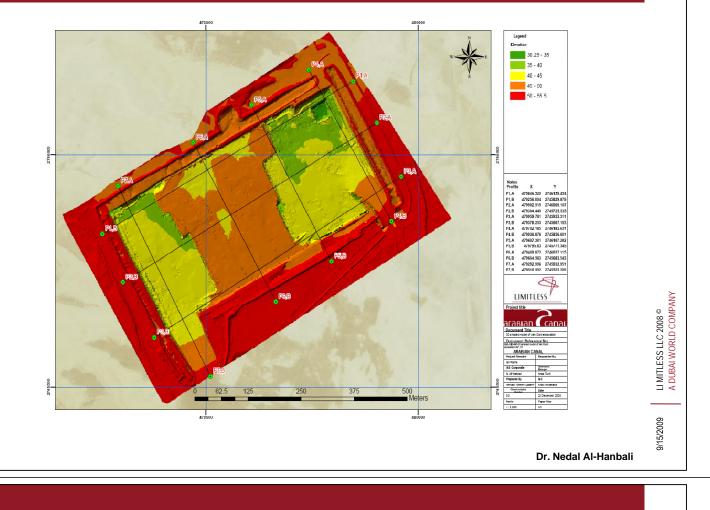
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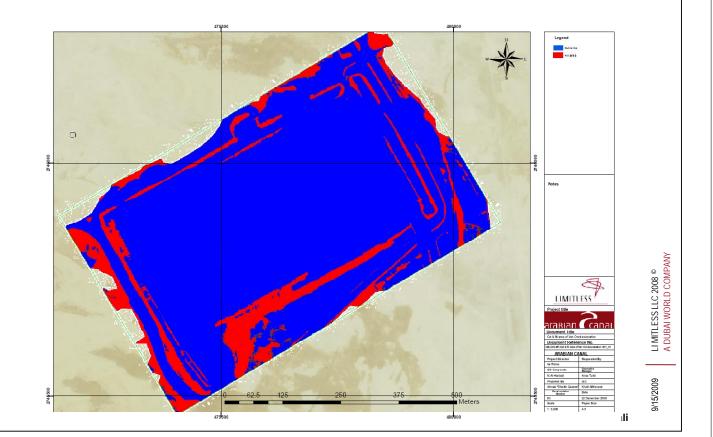
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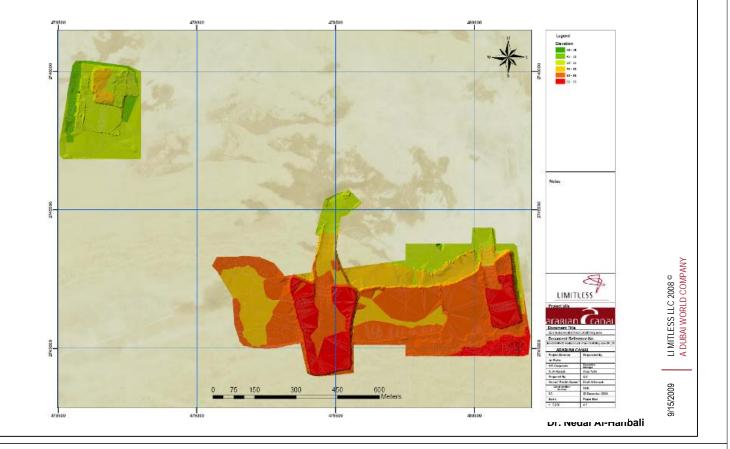
3D Volume Map, Dig



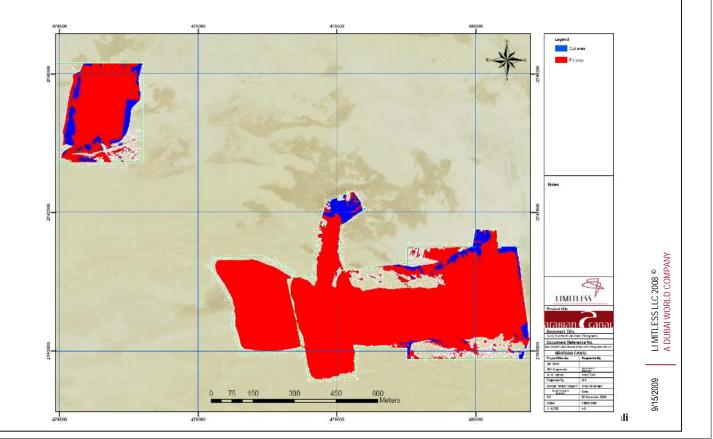
Cut/Fill Area wrt Base Survey

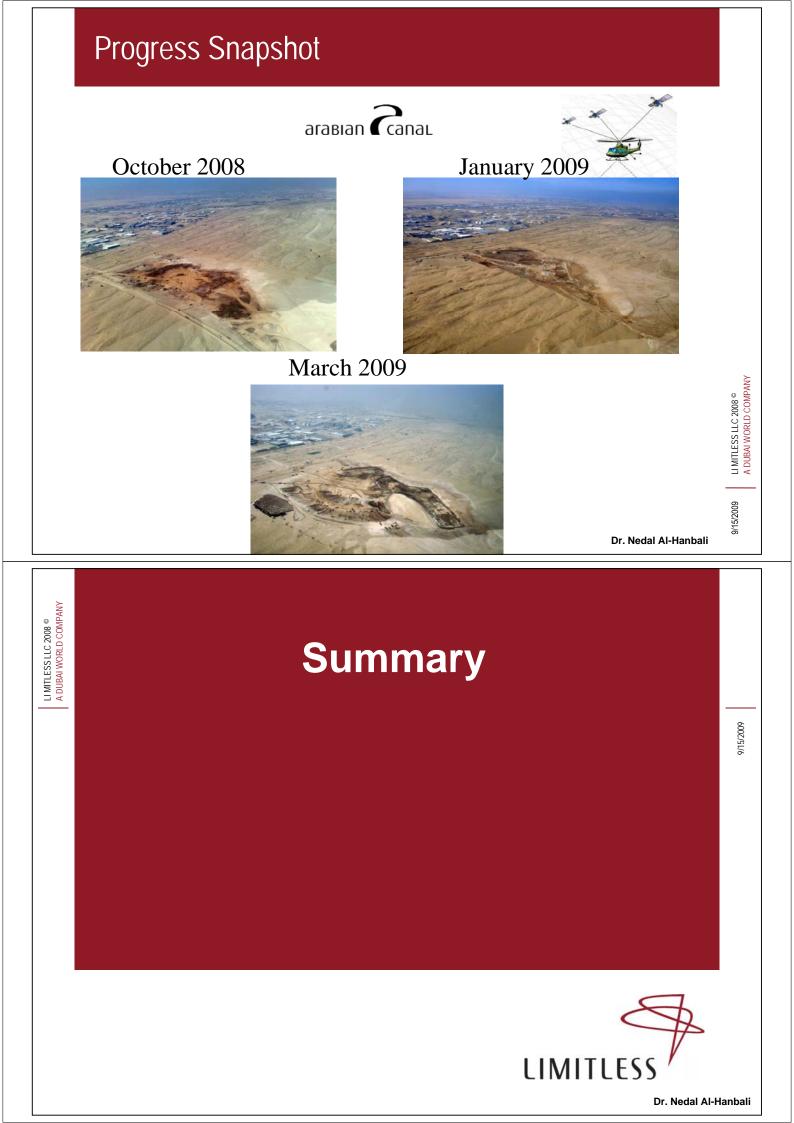


3D Volume Map, Deposit



Cut/Fill Areas wrt Base Survey





Conclusion

Limitless Geomatics Information System Department has proven that an integrated airborne and land mobile mapping system is the preferred approach for earthwork monitoring for the Arabian Canal project:

ITraditional earthwork monitoring surveying techniques imposed a significant risk as far as data acquisition completion during the allocated time.

ITraditional techniques could have resulted in huge cost overruns if earthwork progress had been delayed and not detected on time.

Higher mobile mapping system cost is well absorbed due to its efficiency over traditional techniques, especially in large areas

Mobile Mapping systems provide high accuracy and short turn around compared to traditional techniques

IMobile Mapping systems eliminate schedule risk

Integrated Airborne/land mobile mapping systems reduce any accuracy risk due to their complementary nature.

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Results to Date

- The airborne DSS system can collect 25 km² within four hours of flying, while the LANDMark system covers 100 hectares mapped in an hour
- Final 3D map products meeting accuracy requirements for volume calculation are routinely produced within 1 week:
 - I Current bottlenecks are in the point cloud filtering and redundancy checking
 - I Efforts are underway to automate both and reduce turn-around time to < 3 days

Proven ability to produce accurate measurements in a short time, reinforcing our distinctive, innovative approach to development.

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