

Institut für Photogrammetrie

The EuroSDR Performance Test for Digital Aerial Camera Systems

EuroSDR network on Digital Camera Calibration and Validation



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Michael Cramer

michael.cramer@ifp.uni-stuttgart.de

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	EuroSDR test	DGPF		
Acquisition Time	10/2003, 06/2004, 09/2004	July – September 2008		
Test site	Vaihingen/Enz (1x) Fredrikstad (2x)	Vaihingen/Enz		
Sensor systems	ADS40 (1st), DMC, Ultracam-D	ADS40 (2nd), DMC, Ultracam-X, JAS-150, Quattro DigiCAM, AIC-x1, DLR 3K, RMK-Top, ALS50, AISA, ROSIS, Spectrometer		
Research topics	Geometry	Geometry, Radiometry, DSM Generation, Stereoplotting		
Active participants	13 groups/institutions (European)	30 groups/institutions (German speaking countries)		



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The DGPF-Test Objectives & Organization

- User driven independent and objective evaluation of commercially available digital photogrammetric camera systems (focus on airborne and large format)
- Follow-up of already done national or international evaluation projects (like EuroSDR network Digital Camera Calibration)
- Evaluation of sensor specific strengths and potential weaknesses, no direct comparison between performance of different sensors!
- Processing teams focussing on different topics
 - Team 1: Geometric accuracy and resolution (> K. Jacobsen)
 - Team 2: Radiometric accuracy (▶ M. von Schönermark)
 - Team 3: Automatic DSM genereation (> N. Haala)
 - Team 4: Stereoplotting (V. Spreckels)





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Reference data Test field layout

Ground references

- Spectrometer measurements in field, sunphotometer
- BRDF measurements
- Manual, on-site land use classifications (multiple days)



DGPF evaluation test Vaihingen/Enz test flight data

System	System provider	Flyer	Date of flight(s)		
DMC	Intergraph/ZI	RWE Power	24.7.08 + 6.8.08		
ADS 40, SH52	Leica Geosyst.	Leica Geosyst.	6.8.08		
JAS-150	JenaOptronik	RWE Power	9.9.08		
Ultracam-X	Vexcel Imaging	bsf Swissphoto	11.9.08		
RMK-Top15	Zeiss	RWE Power	24.7.08 + 6.8.08		
quattro DigiCAM, 4-Head	IGI	Geoplana	6.8.08		
AIC-x1, 1-Head	Rolleimetric	Alpha Luftbild	11.9.08		
AIC-x4, 4(3)-Head	Rolleimetric	Vulcan Air	19.9.08		
DLR 3K-Camera	DLR Munich	DLR Munich	15.7.08		
AISA+ hyper-spectral (parallel with DMC)	Specim/FH Anhalt	RWE Power	2.7.08		
ROSIS hyper-spectral	DLR Munich	DLR Munich	15.7.08		
ALS 50 LiDAR Leica Geosyst.		Leica Geosyst.	21.8.08		

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Impact of Self Calibration – GSD 20cm Frame Sensors

Block	#GCP / h _g p / q [%]	
RMK Uni Hann. no SC	14 / 2160m 60 / 70	
RMK <i>Uni Hann.</i> 12 BLUH par. DMC <i>Uni Hann.</i>	14 / 2160m 60 / 70 9 / 2160m	0,10
no SC DMC Uni Hann. 12par.+2 DMC	60 / 60 9 / 2160m 60 / 60	0,05
UCX Uni Hann. no SC UCX Uni Hann. 12par.+32 UC	9 / 2900m 70 / 70 9 / 2900m 70 / 70	0,00 RMK RMK DMC DMC UCX UCX noSC withSC noSC withSC noSC withSC

BLUH results from IPI, Uni Hannover

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RMS from ChP [m]





Absolute Object Point Accuracy – GSD 20cm Frame Sensors

	#GCP/h	0,20	
Block	p / q [%]	0.15	
DMC <i>Uni Hann.</i> 60 photos	9 / 2160m 60 / 60	0,15	
DMC Uni Stuttg. 42 photos	4 / 2160m 60 / 60	0,10 -	
UCX Uni Hann. 52 photos	9 / 2900m 70 / 70		
UCX Uni Stuttg. 36 photos	4 / 2900m 70 / 70	0,05 -	┝╼╗╎╌┛┝┥┫┝┥┫┝┥┫┝
IGI Uni Stuttg. 132 photos	4 / 2500m 60 / 70		
RMK Uni Hann. 47 photos	14 / 2160m 60 / 70	0,00 +	DMC DMC UCX UCX DigiCAM RMK Hann. Stuttg. Hann. Stuttg. Stuttg. Hann.

RMS from ChP [m]

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Absolute Object Point Accuracy – GSD 8cm Frame Sensors

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RMS from ChP [m]

Absolute Object Point Accuracy Line Scanners

Block	# GCP / Height h _a	0,20				GSD	20cm	
ADS Uni Hann. GSD 8cm	9 / 1900m	0,15						
JAS RAG Herne GSD 8cm	0 / 1800m	0.10						
JAS RAG Herne GSD 8cm	4 / 1800m				GSD	8cm		
JAS RAG Herne GSD 8cm	19 / 1800m	0,05	28.52			2.2		
JAS RAG Herne GSD 20cm	4 / 4600m							
JAS RAG Herne GSD 20cm	19 / 4600m	0,00	ADS 9GCP	JAS 0GCP	JAS 4GCP	JAS 19GCP	JAS 4GCP	JAS 19GCP

RMS from ChP [m]







S. Klonus (IGF, Universität Osnabrück)



 Other factors gain in importance (environmental conditions, choice of reference data) and may have larger impact on final accuracy than choice of sensor system itself

Conclusions (2/2)

- Sensor and sensor related software chain is tightly coupled and has to be considered
- All results rely on (one single) DGPF data set only transfer of results to later production environments?

Acknowledgments

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Digital Airborne Camera Performance – The DGPF test Overview and results

> DGPF Project Meeting October 5-6, 2009 Universität Stuttgart

see www.ifp.uni-stuttgart.de/dgpf