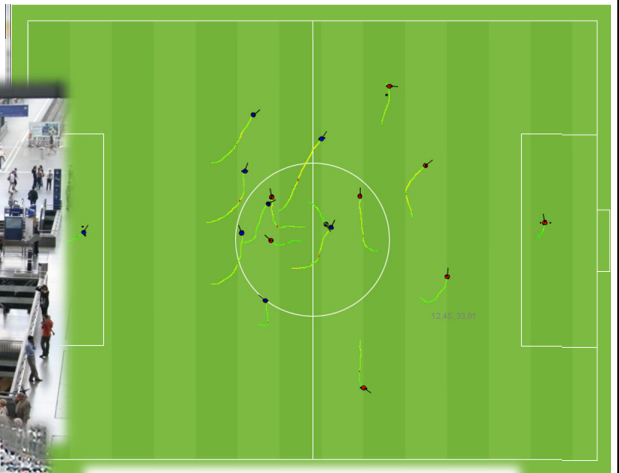


# Interpretation of Moving Point Trajectories

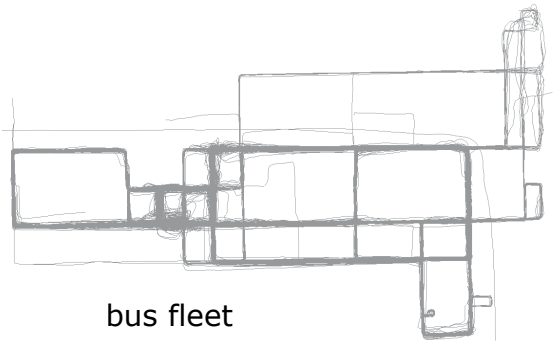
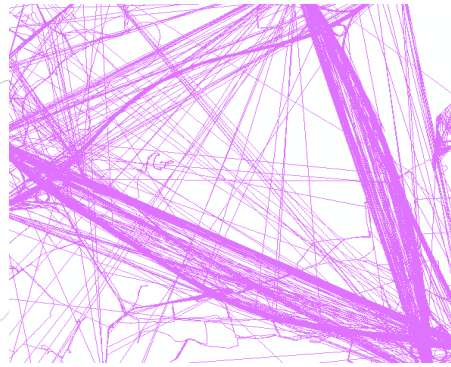
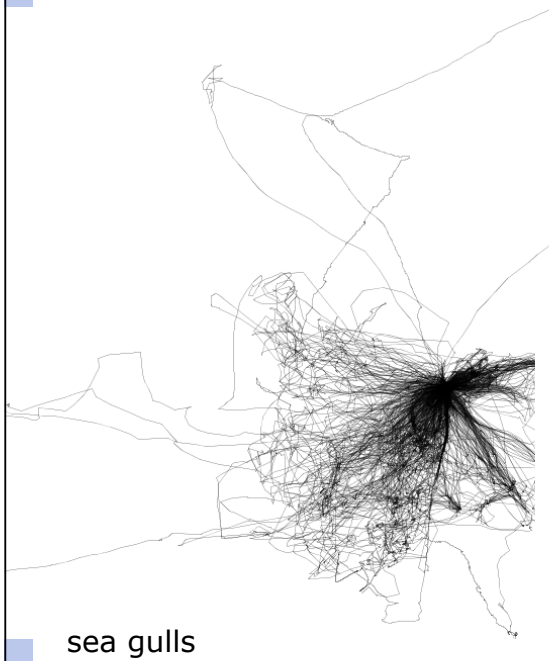
Monika Sester, Udo Feuerhake, Colin Kuntsch,  
Stefania Zourlidou

Institute of Cartography and Geoinformatics  
Leibniz Universität Hannover  
Germany

## Moving point data

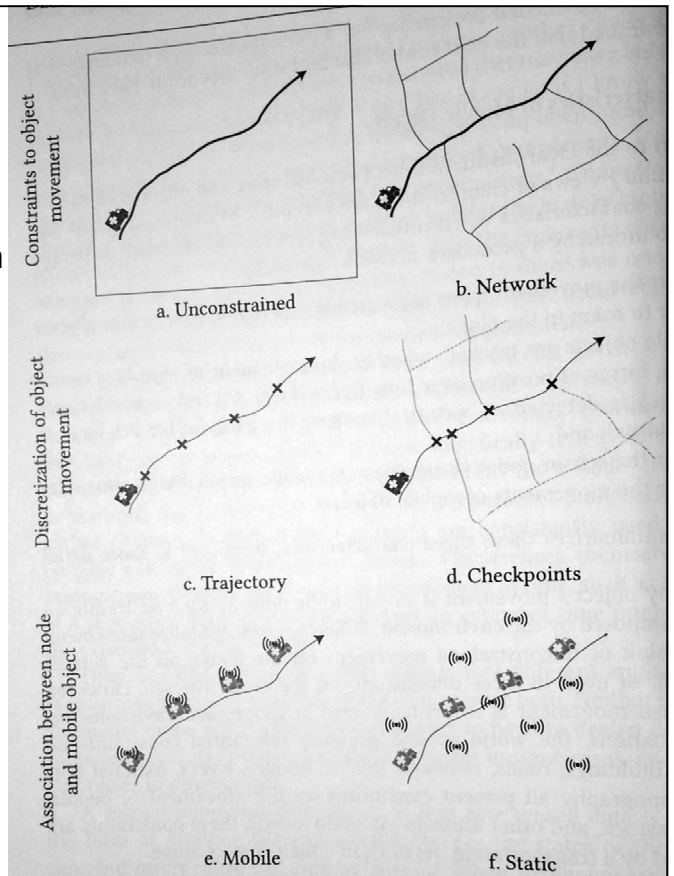


# Trajectories



# Characteristics of moving objects

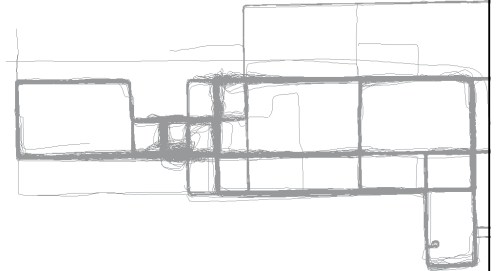
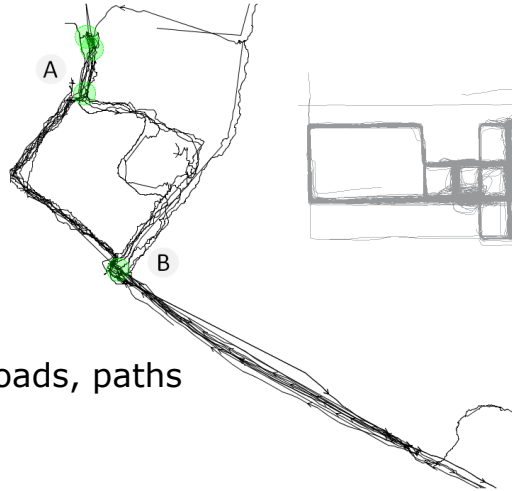
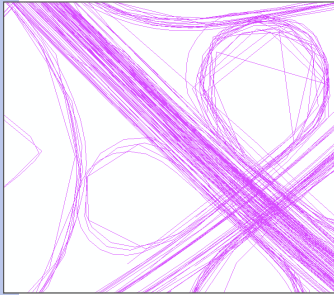
- a. unrestricted movement of object
- b. restricted movement on network
- c. discrete measurement points
- d. measurements at certain locations (anchors)
- e. mobile sensors
- f. static sensors observe moving nodes



Duckham, 2012

# Constrained Movement

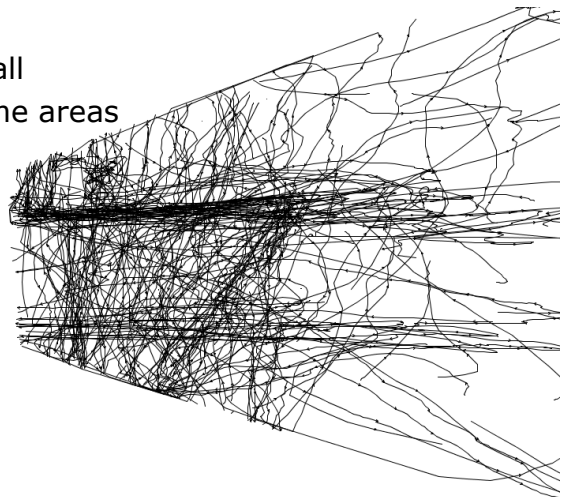
- ▶ .. by road network
  - e.g. Road junction in OSM
  - pedestrian trajectories at LUH
  - Bus fleet



- ▶ „Digitization“ of roads, paths

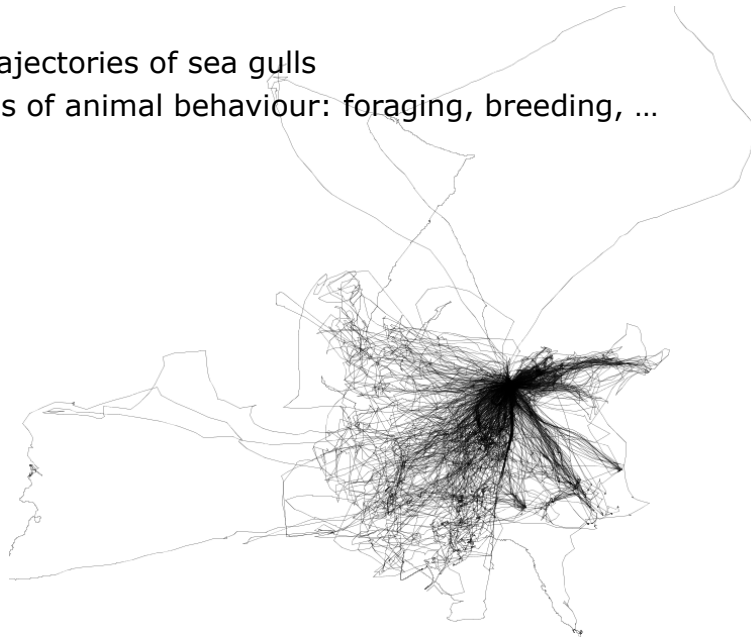
# Constrained Movement

- ▶ By environment:
  - e.g. in a railway station hall: restrictions by kiosks, stairs, elevators, other people
- ▶ Example:
  - Trajectories in university hall
  - temporarily blocking of some areas



# Constrained Movement

- ▶ By behaviour / habits
- ▶ Example:
  - GPS-trajectories of sea gulls
  - analysis of animal behaviour: foraging, breeding, ...



# Moving Point Data

- ▶ Sensor registers movement; inferences possible:
  - individual movement behaviour
  - collective movement behaviour
  - constraints in movement (e.g. paths)
- ▶ Sensors observe (changing) environment
  - e.g. measure temperature, rainfall, distance to objects, ...
  - dense sampling of environmental phenomena (many measurements – possibly of lower quality)
  - inferences possible:
    - environmental maps – of different resolution, thematic depth, ...
    - interpolation of continuous phenomena
- ▶ Analysis
  - central and/or decentral processing
  - pattern detection, clustering, ...

## Types of analyses

- ▶ moving sensors:
  - a) reflect underlying movement constraint
  - b) reflect behaviour
- ▶ (moving) sensors observe environment:
  - a) incremental data acquisition
  - b) collaborative data acquisition

## Interpretation of trajectories

- ▶ determination of underlying infrastructure (e.g. road, path)
- ▶ determination of rules constraining the movement (e.g. traffic rules)
- ▶ determination of movement behavior of individuals or groups
- ▶ determination of unusual behavior of individuals or groups
- ▶ identification of underlying phenomenon (e.g. part of hill which is sliding)

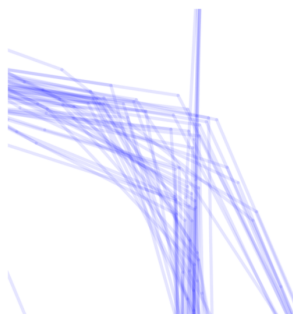
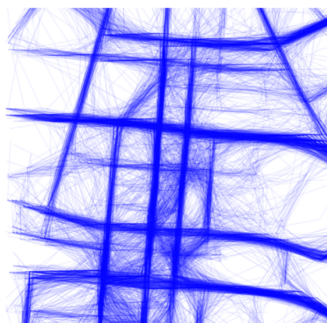
# Extraction of road structure

Colin Kuntzsch



## Data sets ... and challenges

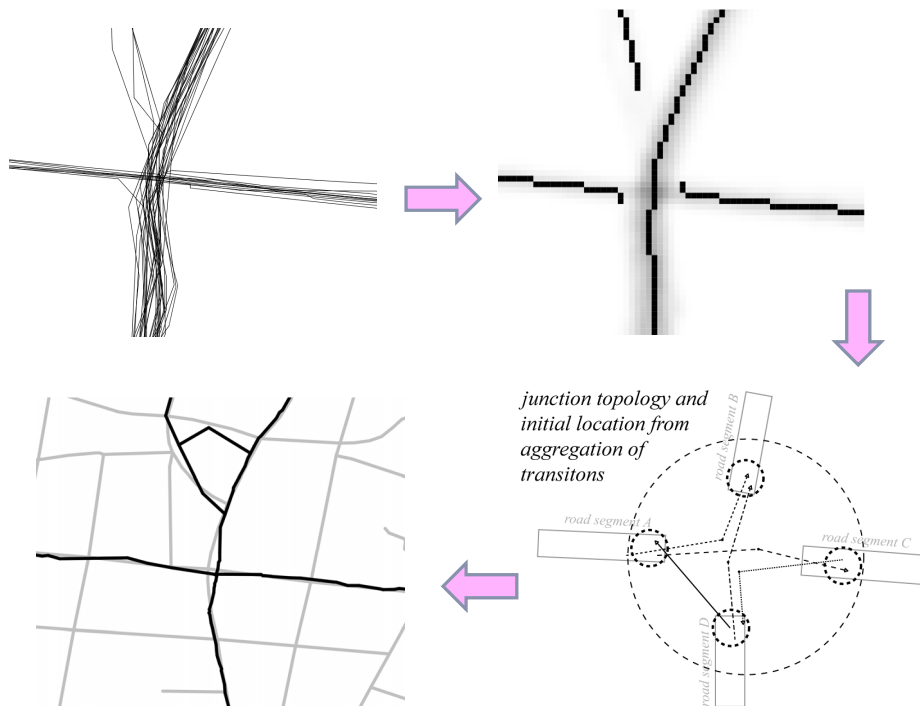
- ▶ Data sets acquired by cars / buses
- ▶ different coverage of roads
- ▶ different accuracy of trajectory locations
  - especially at junctions
  - dependent on sampling rate and position accuracy



# Challenge

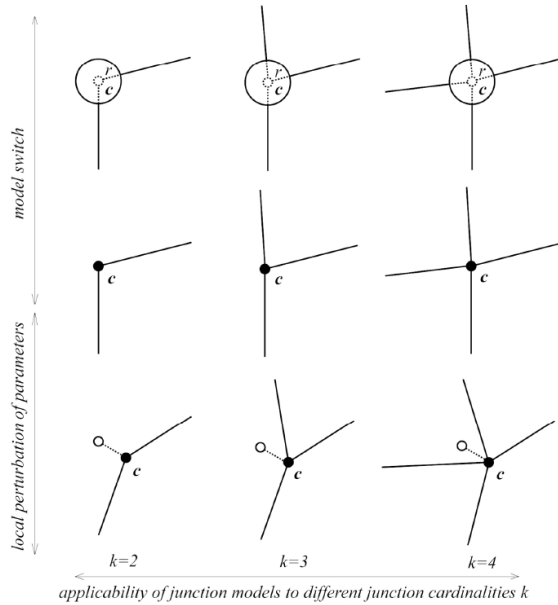
- ▶ Recover individual roads – even if coverage is different
- ▶ Recover junctions
- ▶ Approach:
  - Identify road network using density based approach (KDE) – especially road segments
  - Reconstruct correct location and type of junctions, as well as direction of roads using model based approach

# Approach

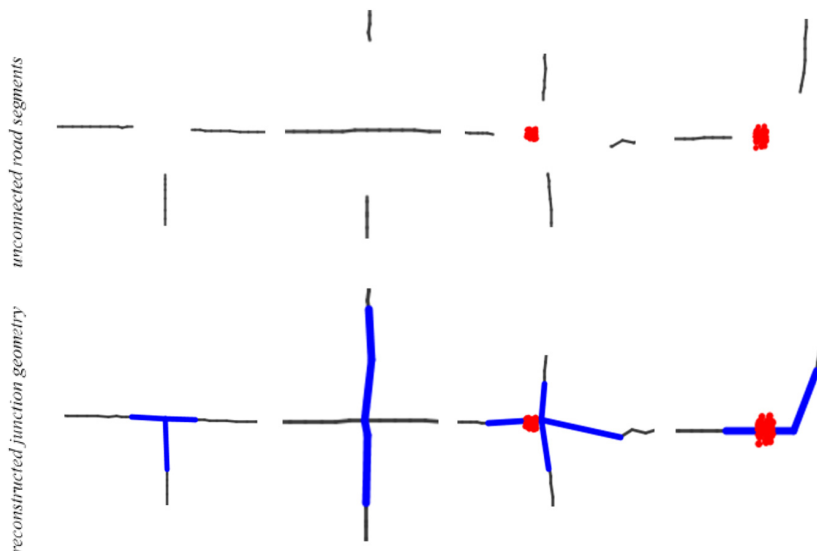


# Junction Model

- ▶ Explore different possibilities of junction types (cardinality) and junction positions

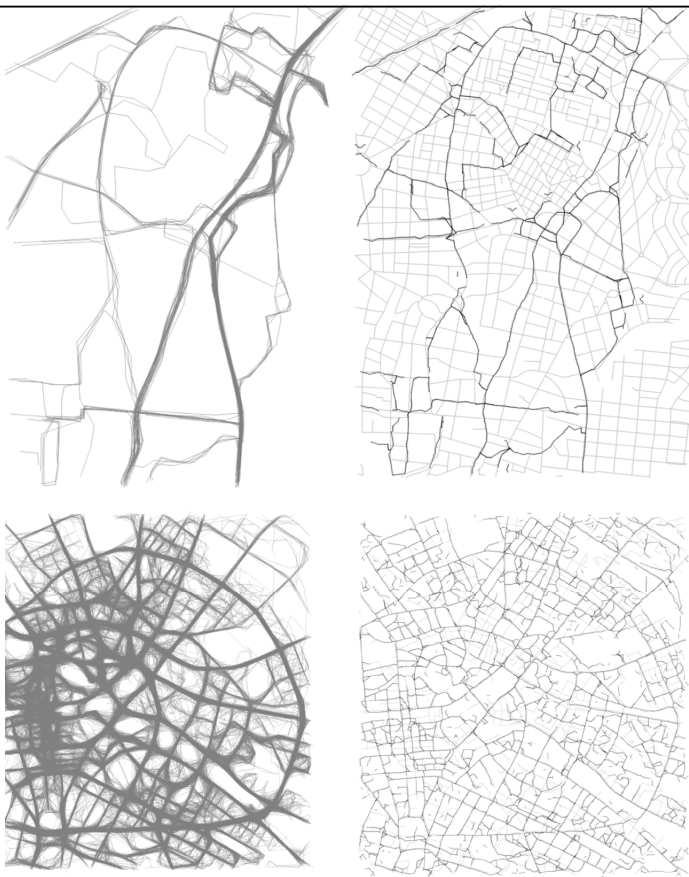


# Result of junction reconstruction

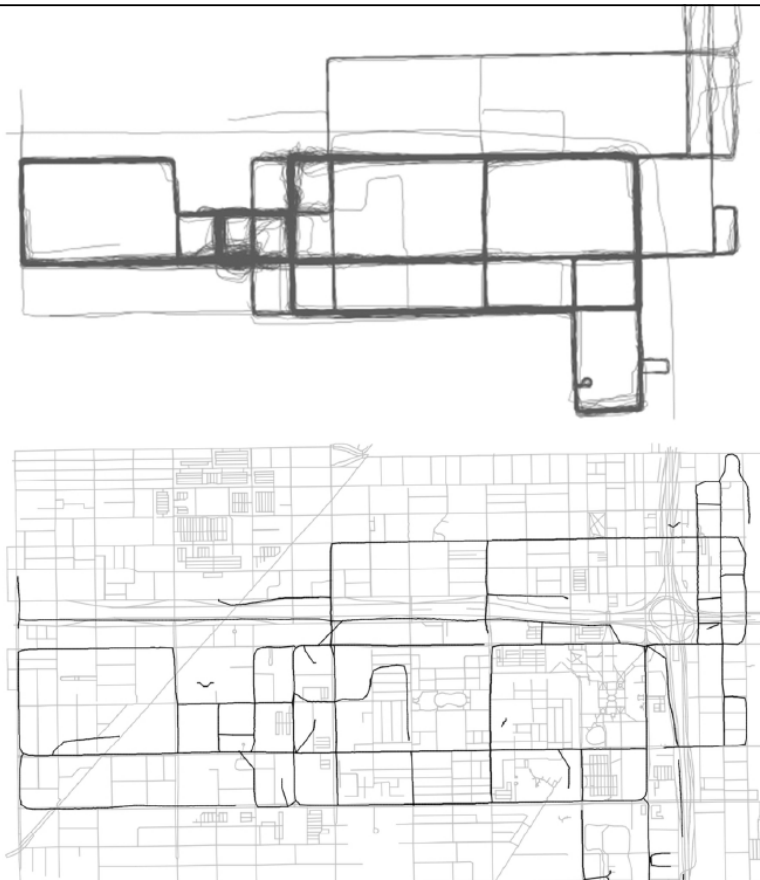




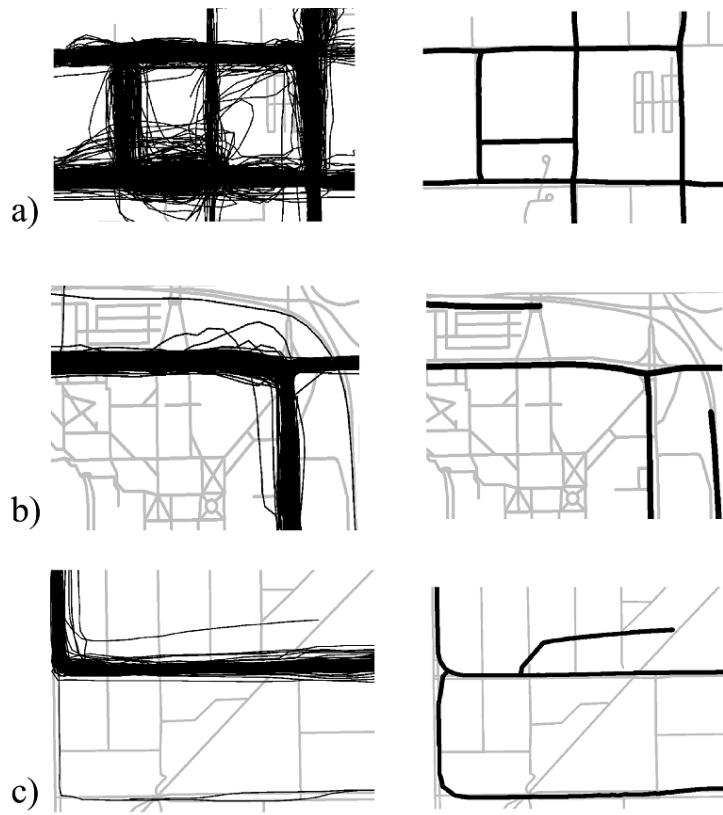
# Results



# Results



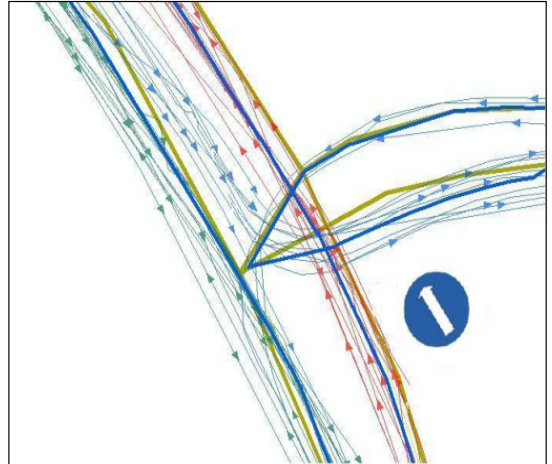
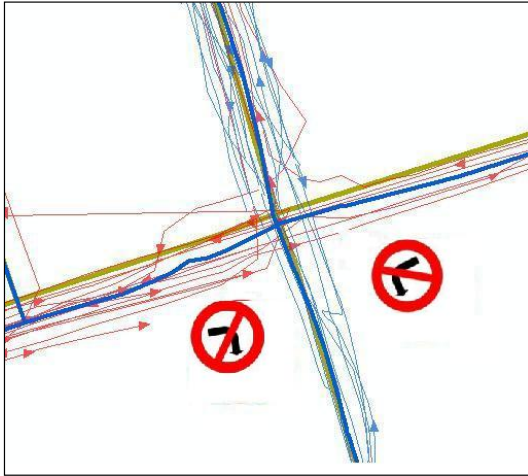
# Results



Extraction of traffic regulations



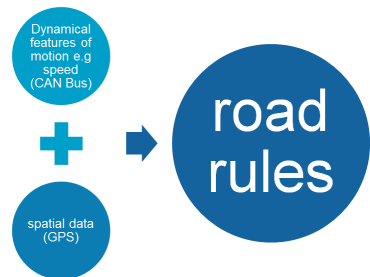
# Derivation of traffic regulations



## Data source

- ▶ In car CAN bus all kinds of information is recorded and stored

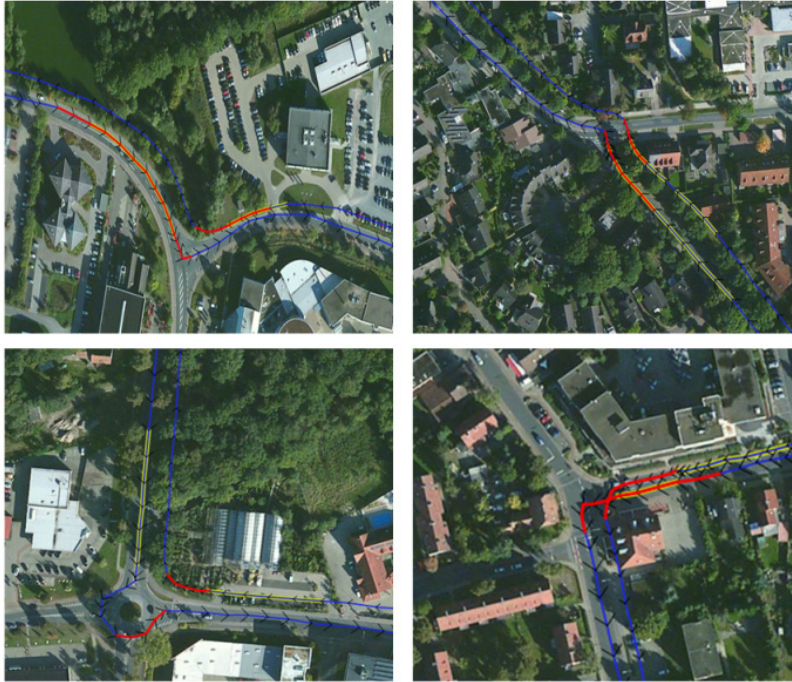
- Position
- velocity
- brake
- blinker
- motor characteristics
- energy consumption
- ...



- ▶ Idea: exploit information to extract
  - traffic rules
  - traffic behaviour of drivers



# Traffic rules / behaviour from trajectories



- ▶ blue: trajectory
- ▶ yellow: break
- ▶ red: blinker
- ▶ assumption: different drivers show similar behaviour in similar situation / location
- ▶ extract rules: speed restrictions, stop, yield, red light, ...

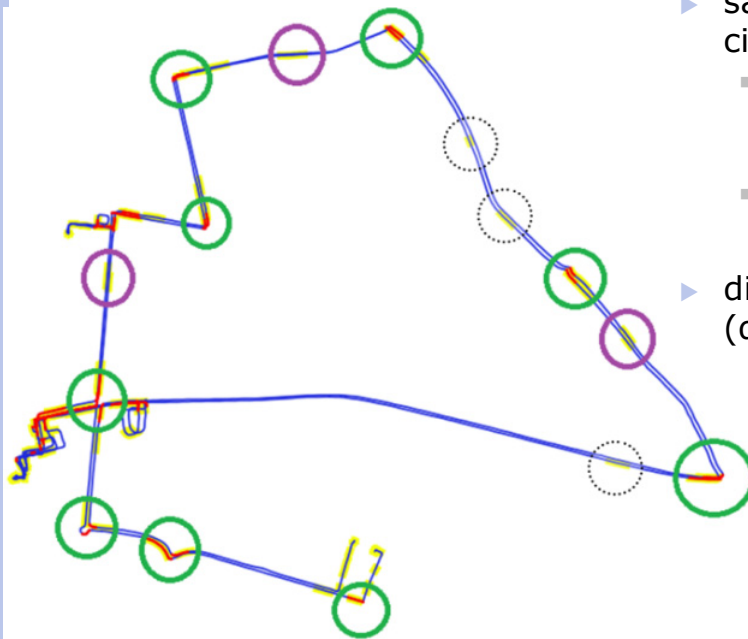


## Two step approach

- ▶ *Clustering of the trajectories:*
  - find clusters of similar trajectories, that is, trajectories that show the same maneuver pattern
  - find clusters of similar pattern at same location
- ▶ *Analysis of the extracted clusters:* given a standard 4-way intersection of two roads:
  - If only a right turn maneuver pattern has been identified (cluster of right turns), a compulsory *right turn* rule is valid.
  - If only a left turn maneuver pattern has been identified, a compulsory *left turn* rule is valid.
  - ....
  - If a stop maneuver pattern is detected, a compulsory stop rule is valid



## Small Example: two trajectories



- ▶ same behaviour (solid circles)
  - green: sequence of blinker (red) and break (yellow) -> turn
  - violet: break
- ▶ different behaviour (dotted circles)

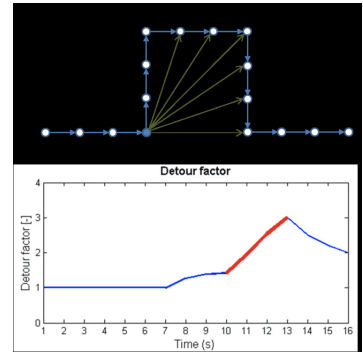
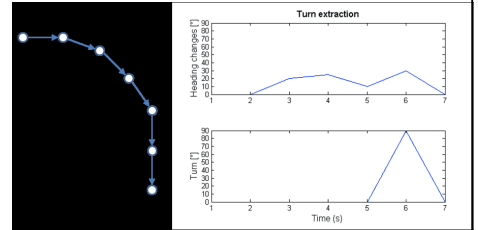
## Interpretation of (atypical) behaviour

# Determination of atypical behaviour

- ▶ Idea: driver shows a specific behaviour when he/she got lost
- ▶ -> offer help!

- ▶ Components of behaviour:
  - dense sequence of turns
  - detour
  - route repetition

- ▶ for each of these components probabilities for typical behaviour are determined
- ▶ fusion of probabilities in Hidden Markov Model

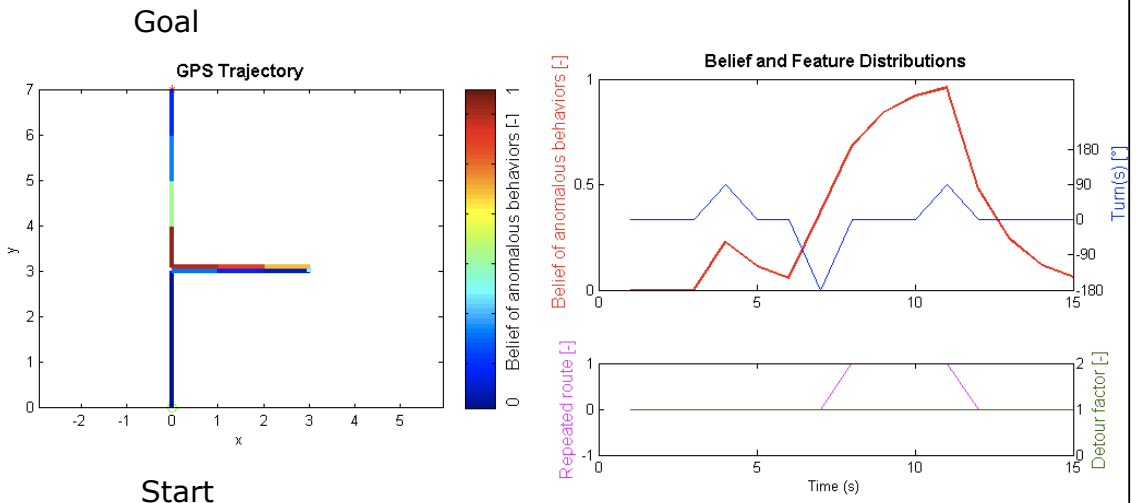


[Huang & Zhang]



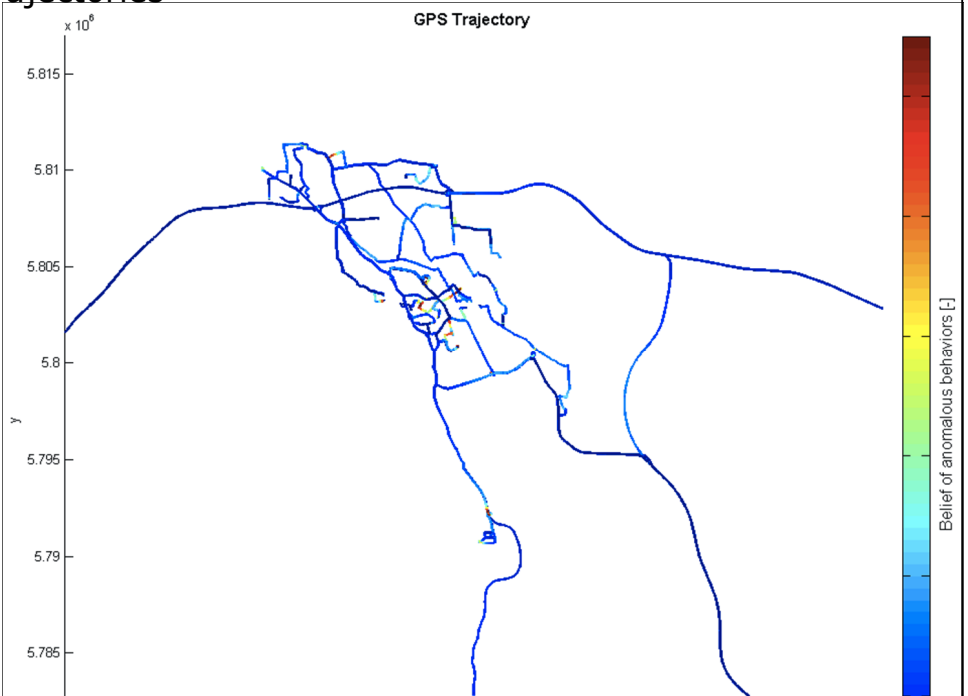
# Determination of atypical behaviour

- ▶ Example: route from bottom to top



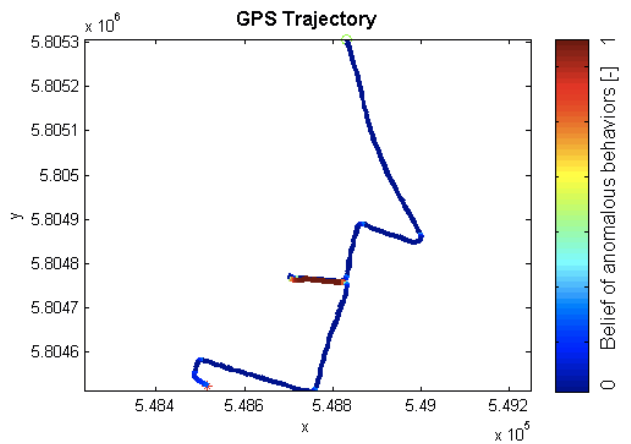
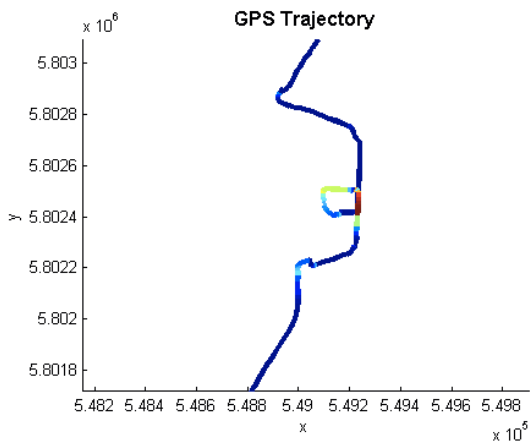
# Determination of atypical behaviour

## ▶ 100 trajectories

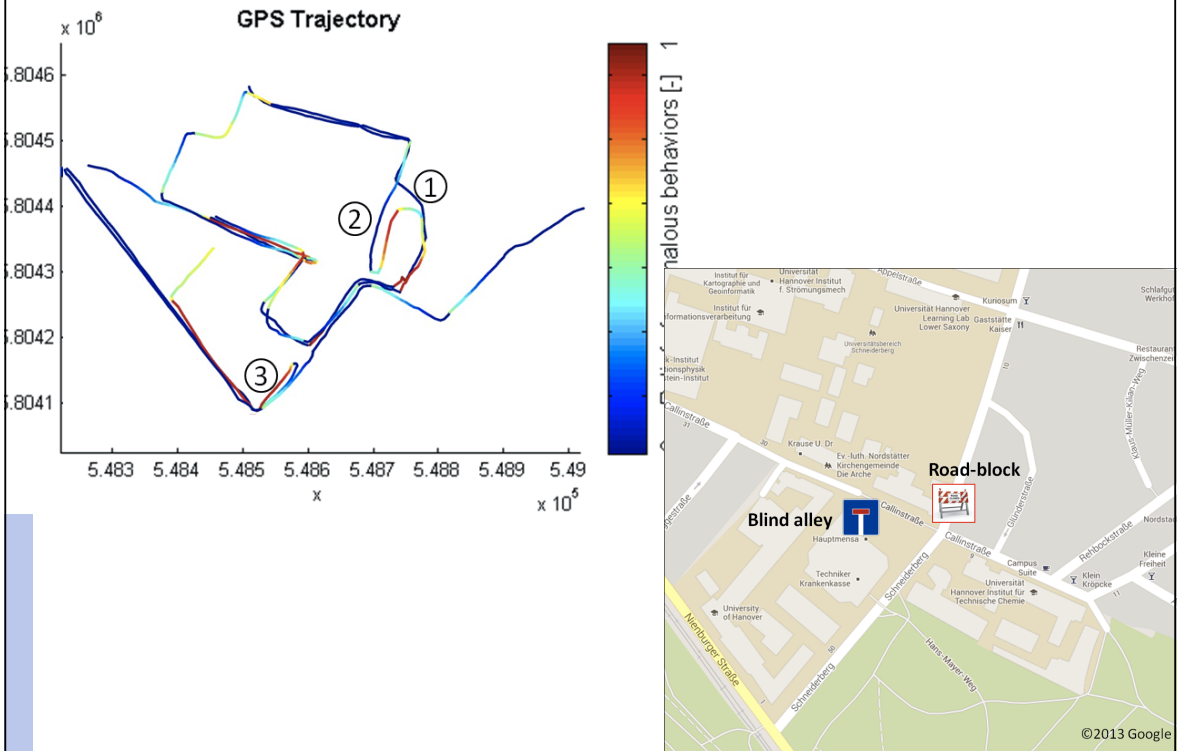


## Examples

### ▶ Details



# Indication of atypical traffic situation



Detection of Group Patterns – in soccer

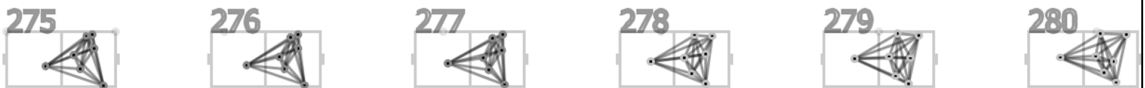
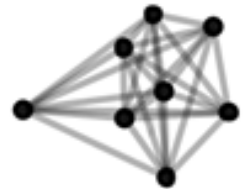


# Team Movement Patterns



# Team Movement Patterns

- ▶ Approach is based on
  - fixed number of players
  - constellations (vector of relative player positions – scale, rotation, translation independent)
- ▶ Sequence of constellations is recorded during the observation time (e.g. at 1Hz)



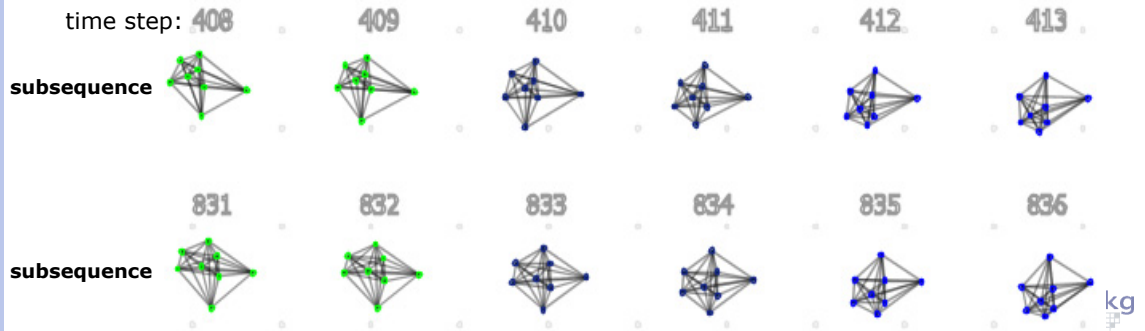
- ▶ Clustering of constellations based on similarities



- ▶ -> Cluster Sequences (e.g. red, red, red, green, green, green, ...)

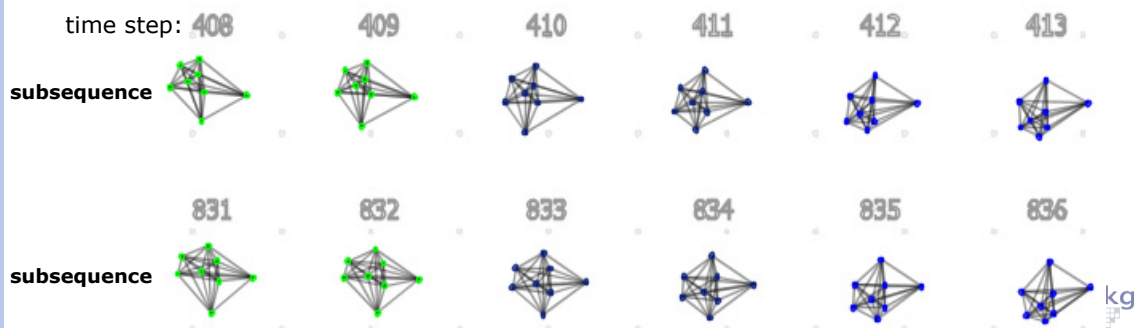
# Team Movement Patterns

- ▶ Use of **sequence mining** algorithm to extract patterns from the sequence of clusters (clustered constellations): same sequence of constellations, e.g.:
  - D,F,A,A,B,C,D,E,F,A,A,B,A,B,C,C, ..
- ▶ Example pattern (occurred twice during the observation time):
  - Transition of constellations green, green, blue, blue, light blue, light blue
  - "three middle players move from top to down"



# Team Movement Patterns

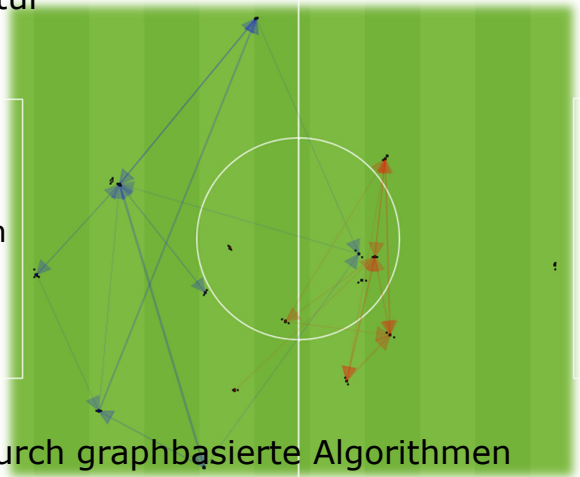
- ▶ Use of **sequence mining** algorithm to extract patterns from the sequence of clusters (clustered constellations): same sequence of constellations, e.g.:
  - D,F,A,A,B,C,D,E,B,A,A,B,A,B,C,C,
- ▶ Example pattern (occurred twice during the observation time):
  - Transition of constellations green, green, blue, blue, light blue, light blue
  - "three middle players move from top to down"



# Weitere Analysen: "Passgraph"

## ▶ Erzeugung einer Graphstruktur

- Knoten ↔ Spieler
- Kanten ↔ Pässe
- Kantengewicht ↔ Anzahl der Pässe zwischen Paaren von Spielern



## ▶ Visuelle Analyse

## ▶ Automatische Auswertung durch graphbasierte Algorithmen

- z.B. häufige Passequenzen
- ...

# Passmuster

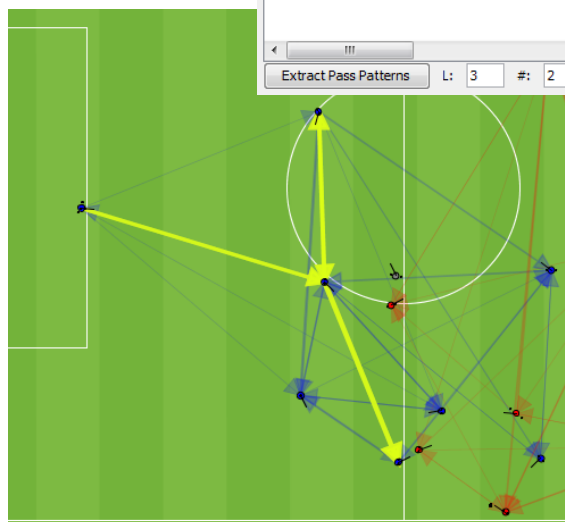
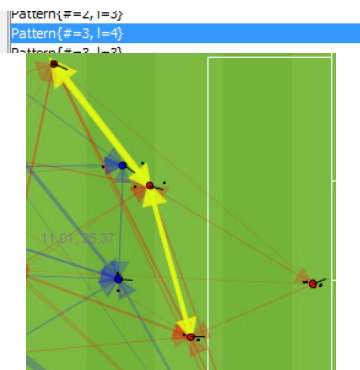
## ▶ Muster aus der Pass-Historie

## ▶ Sequenz Mining Ansatz: Spieler A spielt zu B, der zu C und zurück zu A, ..

```
History Patterns
Pattern(#=2, l=3)
Pattern(#=2, l=4)
Pattern(#=2, l=3)

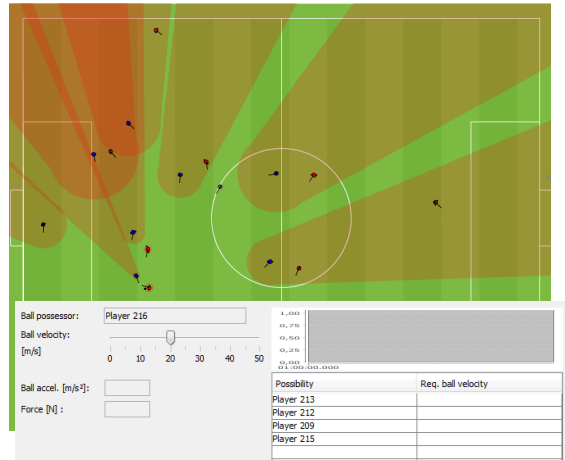
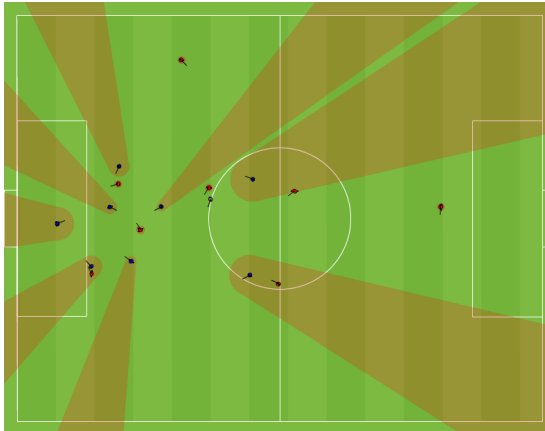
Pattern(#=2, l=4)
->Completed pass: Player 201 -> Player 204->Completed pass: Pla
->Completed pass: Player 201 -> Player 204->Completed pass: Pla

Extract Pass Patterns L: 3 #: 2
```



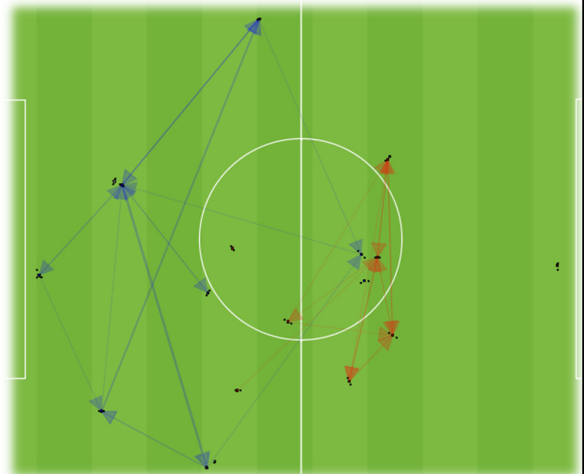
# Mögliche Pass-Empfänger

- ▶ Bestimmung der überdeckten Flächen
  - Abhängig vom Bewegungsmodell der Spieler und des Balls
  - Manuelle Variation der Passgeschwindigkeit möglich
- ▶ Interessant: Bestimmung der optimalen Passgeschwindigkeit!



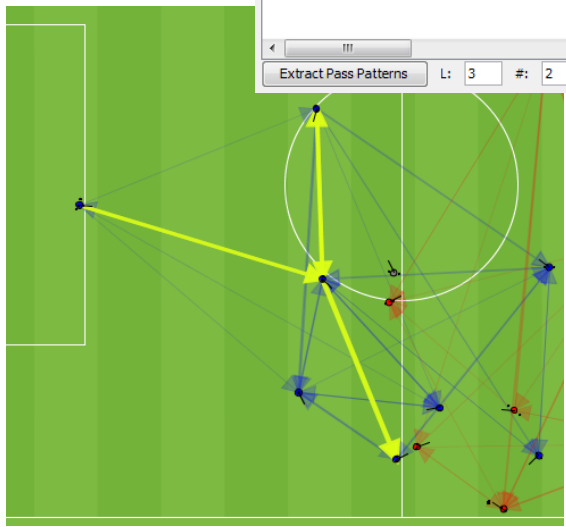
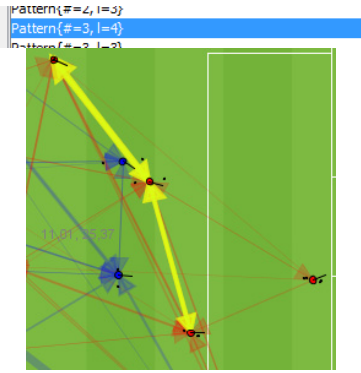
# Advanced Analyses: Pass Graph

- ▶ Generation of a graph structure
  - Nodes ↔ players
  - Edges ↔ passes
  - Edge weight ↔ frequency of passes between pair of players
- ▶ Visual analysis is possible
- ▶ Analysis via graph based algorithms
  - Frequent pass sequences
  - ...



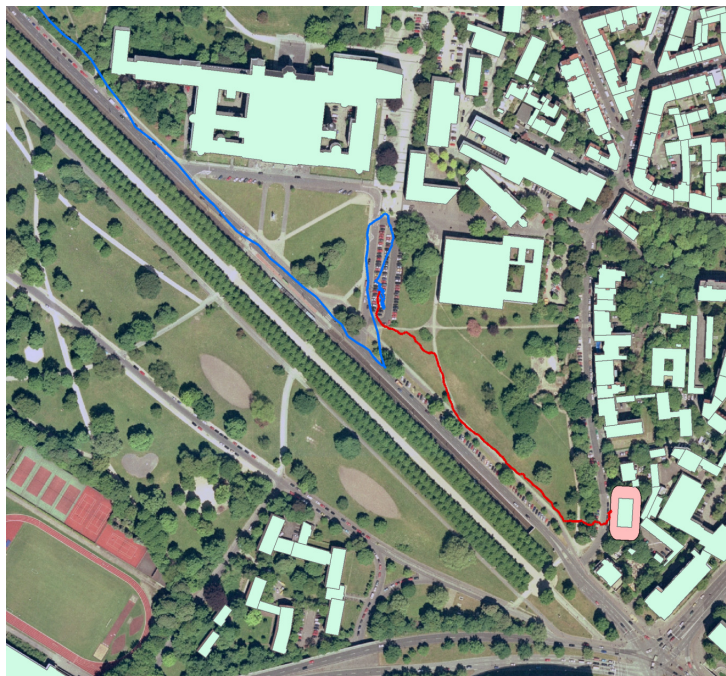
# Advanced Analyses: Pass Patterns

- ▶ Patterns are extracted from pass history
- ▶ Mining approach similar to the 'team movement pattern' approach



# Analysis of typical transitions between modes

- ▶ E.g. car -> walk: identify parking spaces associated with entrances



# Interpretation of movement behaviour

- ▶ Moving point data are being acquired by different sensors (e.g. cameras, GPS, Mobile phones, ...) and for different purposes and applications (e.g. animal behaviour analysis, surveillance, ...)
- ▶ Two projects dealing with interpretation of movement behaviour
  - Determination of group patterns
  - Determination of typical behaviour and movement prediction

## Summary

# Summary

- ▶ More and more trajectory data are available
- ▶ Trajectory data contain rich information concerning **behaviour** and **underlying structure**
  
- ▶ Relevant applications:
  - Analysis of animal behaviour
  - Analysis of typical/atypical behaviour
  - Capture of up-to-date environmental information (e.g. traffic jams, usage of infrastructure, ...)
  
- ▶ Challenges
  - large data sets / streaming data
  - integration of different data sets
  - generic analysis methods
  - decentralized processing
  - data ownership and privacy